

# Operating Instructions IR5D001 Inductive Ring Sensor





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# 1 General

## 1.1 Information Concerning these Instructions

- These instructions make it possible to use the product safely and efficiently.
- These instructions are an integral part of the product and must be kept on hand for the entire duration of its service life.
- Local accident prevention regulations and national work safety regulations must be complied with as well.
- The product is subject to further technical development, and thus the information contained in these operating instructions may also be subject to change. The current version can be found at www.wenglor.com in the product's separate download area.



### **INFORMATION**

The operating instructions must be read carefully before using the product and must be kept on hand for later reference.

## 1.2 Explanation of Symbols

· Safety precautions and warnings are emphasized by means of symbols and signal words.

• Safe use of the product is only possible if these safety precautions and warnings are adhered to.

The safety precautions and warnings are laid out in accordance with the following principle:

#### SIGNAL WORD

#### Type and source of danger!

Possible consequences in the event that the hazard is disregarded.

 $\rightarrow$  Measures for averting the hazard.

The meanings of the signal words, as well as the scope of the associated hazards, are listed below:



## 

This signal word indicates a hazard with a high degree of risk which, if not avoided, results in death or severe injury.



## 

This signal word indicates a hazard with a medium degree of risk which, if not avoided, may result in death or severe injury.



### 

This signal word indicates a hazard with a low degree of risk which, if not avoided, may result in minor or moderate injury.



### NOTICE

This signal word draws attention to a potentially hazardous situation which, if not avoided, may result in property damage.



### **INFORMATION**

Information draws attention to useful tips and suggestions, as well as information on efficient, error-free use.

## 1.3 Limitation of Liability

- The product has been developed in consideration of the current state-of-the-art technology, as well as applicable standards and guidelines. Subject to change without notice.
- A valid declaration of conformity can be accessed at www.wenglor.com in the product's separate download area.
- wenglor sensoric elektronische Geräte GmbH (hereinafter referred to as "wenglor") excludes all liability in the event of:
  - Non-compliance with the instructions
  - Use of the product for purposes other than those intended.
  - Use by untrained personnel.
  - Use of unapproved spare parts.
  - Unapproved modification of products.
- These operating instructions do not include any guarantees from wenglor with regard to the described procedures or specific product characteristics.
- wenglor assumes no liability for printing errors or other inaccuracies contained in these operating instructions unless wenglor was verifiably aware of such errors at the point in time at which the operating instructions were prepared.

# 1.4 Copyrights

- The contents of these instructions are protected by copyright law.
- All rights are reserved by wenglor.
- Commercial reproduction or any other commercial use of the provided content and information, in particular graphics and images, is not permitted without previous written consent from wenglor.

# 2 For Your Safety

## 2.1 Use for Intended Purpose

This wenglor product is intended for use in accordance with the following functional principle:

#### Inductive Sensors with Increased Switching Distance

Inductive sensors are used to detect the position of metallic objects. A coil is located underneath the sensing face of inductive sensors which generates a magnetic field. Approaching metal objects (e.g. steel, aluminum or brass) generate eddy currents within this magnetic field which are measured by the sensor. When the approaching metal object reaches the selected switching distance, the output is switched.

#### This product can be used in the following industry sectors:

- Special-purpose mechanical engineering
- · Heavy mechanical engineering
- Logistics
- Automotive industry
- · Food industry
- · Packaging industry
- Pharmaceuticals industry
- · Plastics industry
- Woodworking industry

- Consumer goods industry
- Paper industry
- Electronics industry
- · Glass industry
- Steel industry
- · Aviation industry
- Chemicals industry
- · Alternative energies
- Raw materials extraction

### 2.2 Use for Other than the Intended Purpose

- Not a safety component in accordance with 2006/42/EC (Machinery Directive).
- The product is not suitable for use in potentially explosive atmospheres.
- The product may be used only with accessories supplied or approved by wenglor, or in combination with approved products. A list of approved accessories and combination products can be found at www.wenglor.com on the product detail page.



### **A** DANGER

#### Risk of personal injury or property damage in case of use for other than the intended purpose!

Use for other than the intended purpose may lead to hazardous situations.

→ Observe instructions regarding use for intended purpose.

## 2.3 Personnel Qualifications

- Suitable technical training is a prerequisite.
- In-house electronics training is required.
- Trained personnel who use the product must have (permanent) access to the operating instructions.



### ▲ DANGER

Risk of personal injury or property damage in case of incorrect initial start-up and maintenance!

Personal injury and damage to equipment may occur.

 $\rightarrow$  Adequate training and qualification of personnel

## 2.4 Modification of Products



### **▲ DANGER**

#### Risk of personal injury or property damage if the product is modified!

Personal injury and damage to equipment may occur. Noncompliance may result in loss of the CE mark and voiding of the warranty.

 $\rightarrow$  Modification of the product is not permitted

## 2.5 General Safety Precautions



### INFORMATION

These instructions are an integral part of the product and must be kept on hand for the entire duration of its service life.

In the event of possible changes, the current version of the operating instructions can be found at www.wenglor.com in the product's separate download area.

Read the operating instructions carefully before using the product.

Protect the sensor against contamination and mechanical influences.

## 2.6 Approvals and Protection Class



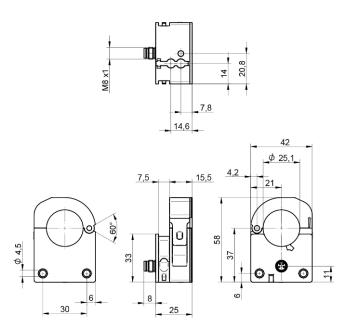
# 3 Technical Data

## 3.1 General Data

| Technical Data                                 | IR5D001               |  |  |  |  |  |  |
|--|-----------------------|--|--|--|--|--|--|
| Inductive Data                                 |                       |  |  |  |  |  |  |
| Inside diameter                                | 25,1 mm               |  |  |  |  |  |  |
| Functional principle                           | static                |  |  |  |  |  |  |
| Smallest recognizable object (Ø)               | 4 mm*                 |  |  |  |  |  |  |
| Correction Factors Stainless Steel V2A/CuZn/Al | 1/1/1                 |  |  |  |  |  |  |
| Electrical Data                                |                       |  |  |  |  |  |  |
| Supply Voltage                                 | 10 30 V DC            |  |  |  |  |  |  |
| Stromaufnahme (Ub = 24 V)                      | < 20 mA               |  |  |  |  |  |  |
| Object speed                                   | 0,1 50 m/s            |  |  |  |  |  |  |
| Response Time                                  | < 300 µs              |  |  |  |  |  |  |
| Ready-state delay                              | < 1,5 s               |  |  |  |  |  |  |
| Switching Output Voltage Drop                  | 1,5 V                 |  |  |  |  |  |  |
| Temperature Range                              | 0 60 °C               |  |  |  |  |  |  |
| Short Circuit Protection                       | yes                   |  |  |  |  |  |  |
| Reverse Polarity and Overload Protection       | yes                   |  |  |  |  |  |  |
| Switching Output/Switching Current             | 100 mA                |  |  |  |  |  |  |
| Interface                                      | IO-Link V1.1          |  |  |  |  |  |  |
| Mechanical Data                                |                       |  |  |  |  |  |  |
| Connection                                     | M8 × 1; 4-pin         |  |  |  |  |  |  |
| Setting Method                                 | Potentiometer/IO-Link |  |  |  |  |  |  |
| Hanger opening/closing cycles                  | max. 100              |  |  |  |  |  |  |
| Degree of Protection                           | IP54                  |  |  |  |  |  |  |
| Adjustable Parameters                          |                       |  |  |  |  |  |  |
| Output   | PNP                   |  |  |  |  |  |  |
|  | Push-Pull             |  |  |  |  |  |  |
|  | NPN                   |  |  |  |  |  |  |
| Circiut  | NO                    |  |  |  |  |  |  |
|  | NC                    |  |  |  |  |  |  |
|  | NC/NO                 |  |  |  |  |  |  |
| Pulse extension                                | 200 ms                |  |  |  |  |  |  |
| Other parameters                               | Sensitivity           |  |  |  |  |  |  |
|  | Error indicator       |  |  |  |  |  |  |
|  | Frequency switching   |  |  |  |  |  |  |
| Output   | PNP                   |  |  |  |  |  |  |
|  | NO                    |  |  |  |  |  |  |
| Technical Safety Data                          |                       |  |  |  |  |  |  |
| MTTFd (EN ISO 13849-1)                         | 1019,99               |  |  |  |  |  |  |
|  |                       |  |  |  |  |  |  |

\* Relates to a steel ball

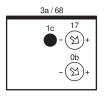
## 3.2 Housing Dimensions



Dimensions specified in mm (1 mm = 0.03937 Inch)

## 3.3 Control Panel

T19



| 0b = pulse length adjuster                      |  |  |  |  |  |
|---|--|--|--|--|--|
| 1c = status display/setup aid                   |  |  |  |  |  |
| 3a = switching status indicator/error indicator |  |  |  |  |  |
| 17 = sensitivity adjuster                       |  |  |  |  |  |
| 68 = supply voltage indicator                   |  |  |  |  |  |

## 3.4 Complementary Products

wenglor offers you the right connection and mounting technology as well as other accessories for your product. You can find this at www.wenglor.com on the product details page at the bottom.

## 3.5 Scope of Delivery

- Sensor
- Soft binder
- Safety precaution

# 4 Transport and Storage

### 4.1 Transport

Upon receipt of shipment, the goods must be inspected for damage in transit. In the case of damage, conditionally accept the package and notify the manufacturer of the damage. Then return the device, making reference to damage in transit.

## 4.2 Storage

The following points must be taken into consideration with regard to storage:

- Do not store the product outdoors.
- Store the product in a dry, dust-free place.
- Protect the product against mechanical impacts.
- Protect the product against exposure to direct sunlight.



### NOTICE

#### Risk of property damage in case of improper storage!

The product may be damaged.

 $\rightarrow$  Storage instructions must be complied with.

# 5 Installation and Electrical Connection

### 5.1 Installation

- Protect the product from contamination during installation.
- Observe all applicable electrical and mechanical regulations, standards and safety rules.
- Protect the product against mechanical influences.
- Make sure that the sensor is mounted in a mechanically secure fashion.
- Specified torque values must be complied with (see section Technical Data [> 8]).
- The active surface of the sensor may not contact any other machine parts.
- Installation regulations must be complied with (see section Technical Data).



### NOTICE

#### Risk of property damage in case of improper installation!

The product may be damaged!

 $\rightarrow$  Comply with installation instructions.



### **⚠ CAUTION**

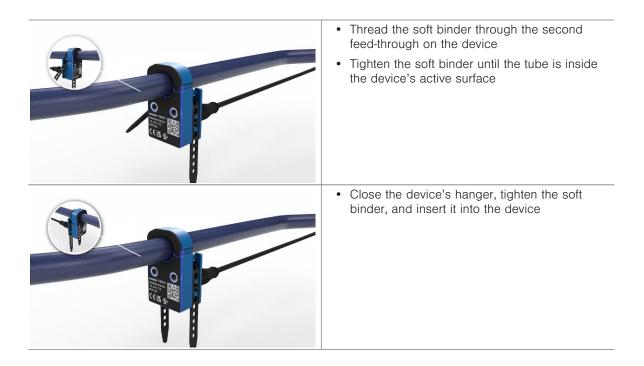
#### Risk of personal injury or property damage during installation!

Personal injury and damage to the product may occur.

 $\rightarrow$  Ensure a safe installation environment.

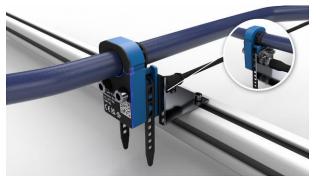
### 5.1.1 Installation Using the Soft Binder



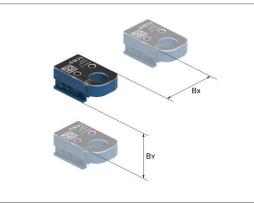


### 5.1.2 Other Installation Options

As a further installation option, the sensor has two holes that can be used to install the sensor using mounting technology. Please note that suitable mounting technology must be provided by the customer. The maximum tightening torque when using an M4 mounting screw is 2.9 Nm. In addition, the minimum installation distance to metal (cf. Technical Data) must be maintained.

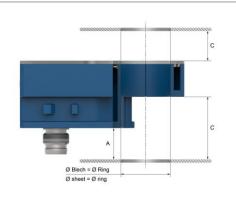


### 5.1.3 Installation Instructions



Adjacent devices alternating between alternative frequency / without alternative frequency

|                | IR5D001 |
|----------------|---------|
| A              | 0       |
| B <sub>x</sub> | 0       |
| В <sub>Y</sub> | 0       |
| С              | 10      |



| Adjacent devices with the same frequency setting |     |  |  |  |  |  |
|--|-----|--|--|--|--|--|
| IR5D001  |     |  |  |  |  |  |
| A  | 0   |  |  |  |  |  |
| B <sub>x</sub>                                   | 42  |  |  |  |  |  |
| B <sub>Y</sub>                                   | 100 |  |  |  |  |  |
| С  | 10  |  |  |  |  |  |

### 5.1.4 Smallest Recognizable Object

The smallest recognizable object indicates the minimum size of a steel ball that can be reliably detected by the sensor. The correction factor 1 can be used to derive the specified resolution with other materials such as stainless steel, brass, or aluminum.

## 5.2 Electrical Connection

- Wire the sensor in accordance with the connection diagram.
- Switch on the supply voltage (see section Technical Data [ 8]).
- If using IO-Link, connect the sensor to 18...30 V DC.
- If not using IO-Link, connect the sensor to 10...30 V DC.
- Alternative frequency activated: Pin 2 to +
- Alternative frequency deactivated: Pin 2 to 0/open

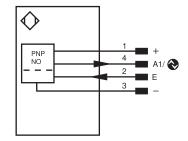
# 

#### Risk of personal injury or property damage due to electric current.

Voltage-conducting parts may cause personal injury or damage to equipment.

ightarrow The electric device may be connected by appropriately qualified personnel only.

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| Leger               | ıd                              |            | PT    | Platinum measuring resistor    | ENAR  | 22 Encoder A/Ā (TTL)          |
|---------------------|---------------------------------|------------|-------|--------------------------------|-------|-------------------------------|
| +                   | Supply Voltage +                |            | nc    | not connected                  | ENBR  | Encoder B/B (TTL)             |
| -                   | Supply Voltage 0 V              |            | U     | Test Input                     | ENA   | Encoder A                     |
| ~                   | Supply Voltage (AC Voltage)     |            | Ū     | Test Input inverted            | ENв   | Encoder B                     |
| А                   | Switching Output                | (NO)       | W     | Trigger Input                  | Amin  | Digital output MIN            |
| Ā                   | Switching Output                | (NC)       | W -   | Ground for the Trigger Input   | Амах  | Digital output MAX            |
| V                   | Contamination/Error Output      | (NO)       | 0     | Analog Output                  | Аок   | Digital output OK             |
| $\overline{\nabla}$ | Contamination/Error Output      | (NC)       | 0-    | Ground for the Analog Output   | SY In | Synchronization In            |
| E                   | Input (analog or digital)       |            | BZ    | Block Discharge                | SY OL | T Synchronization OUT         |
| Т                   | Teach Input                     |            | Amv   | Valve Output                   | Olt   | Brightness output             |
| Z                   | Time Delay (activation)         |            | а     | Valve Control Output +         | м     | Maintenance                   |
| S                   | Shielding                       |            | b     | Valve Control Output 0 V       | rsv   | reserved                      |
| RxD                 | Interface Receive Path          |            | SY    | Synchronization                | Wire  | Colors according to IEC 60757 |
| TxD                 | Interface Send Path             |            | SY-   | Ground for the Synchronization | BK    | Black                         |
| RDY                 | Ready                           |            | E+    | Receiver-Line                  | BN    | Brown                         |
| GND                 | Ground                          |            | S+    | Emitter-Line                   | RD    | Red                           |
| CL                  | Clock                           |            | ÷     | Grounding                      | OG    | Orange                        |
| E/A                 | Output/Input programmable       |            | SnR   | Switching Distance Reduction   | YE    | Yellow                        |
| ۲                   | IO-Link                         |            | Rx+/- | Ethernet Receive Path          | GN    | Green                         |
| PoE                 | Power over Ethernet             |            | Tx+/- | Ethernet Send Path             | BU    | Blue                          |
| IN                  | Safety Input                    |            | Bus   | Interfaces-Bus A(+)/B(-)       | VT    | Violet                        |
| OSSD                | Safety Output                   |            | La    | Emitted Light disengageable    | GY    | Grey                          |
| Signal              | Signal Output                   |            | Mag   | Magnet activation              | WH    | White                         |
| BI_D+/-             | Ethernet Gigabit bidirect. data | line (A-D) | RES   | Input confirmation             | PK    | Pink                          |
| EN0 RS42            | Encoder 0-pulse 0-0 (TTL)       |            | EDM   | Contactor Monitoring           | GNY   | Green/Yellow                  |

## 5.3 Troubleshooting

| Error | Possible cause                | Elimination  |
|-------|-------------------------------|--|
| Error |                               | Check the electrical wiring and elimi-<br>nate the short circuit |
|       | Mechanical damage to the coil | Replace the sensor   |
|       | Hanger not closed             | Close the hanger   |

### INFORMATION

#### **Required Action in Case of Fault:**

- 1. Shut down the machine.
- 2. Analyze and eliminate the cause of error with the aid of the diagnostics information.
- 3. If the error cannot be eliminated, please contact wenglor's support department.
- 4. Do not operate in case of indeterminate malfunctioning.
- 5. The machine must be shut down if the error cannot be definitively explained or properly eliminated.



### **A** DANGER

#### Risk of personal injury or property damage in case of non-compliance!

The system's safety function is disabled. Personal injury and damage to equipment may occur.

 $\rightarrow$  Required action as specified in case of fault.

## 6 Functions Overview

This section explains the sensor's functions and LED symbols in more detail.

## 6.1 Function Description

This function description refers to a setting on the potentiometer of the sensor.

### 6.1.1 Starting Up the Product as Supplied

Device is ready for use and can be put into operation.

The sensitivity is at the maximum setting in order to be able to detect the smallest possible objects. The time delay setting is set to 200 ms (turn all the way to the right).

### 6.1.2 Starting Up the Product with User-Defined Settings

When adjusting settings on the device, a distinction can be made between setting the sensitivity and the time delay.

#### 6.1.2.1 Setting the Sensitivity to Object Size

| Turn the potentiometer all the way to the left   | LED symbols according to section LED Symbols<br>[> 18] |
|--|--|
| Guide the object to be detected through the ring (active surface) of the sensor                    |  |
| If the setup aid is off or flashing, turn the poten-<br>tiometer clockwise in the direction of (+) |  |

#### 6.1.2.2 Adjusting the Off-Delay

The sensors are delivered from the factory with the maximum off-delay.

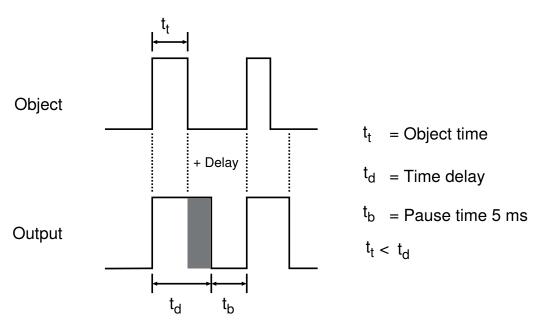
|  | Dynamic                                      |
|--|--|
| <ol> <li>Turn the potentiometer TIME counterclockwise</li> <li>to the desired time delay.</li> </ol> | LED symbols according to section LED Symbols |
| The on-delay is immediately active.  |  |

See also

■ LED Symbols [▶ 18]

### 6.1.2.3 Setting the Pulse Length

The pulse length adjuster can be used to set the time until the signal drops at the output between 5 ms and 200 ms.



If the object is shorter than the set pulse length within the active surface, the switching signal is maintained until the preset off-delay is reached.

### 6.1.2.4 Activating Alternative Frequency

The alternative frequency can be activated either via the cable connection (see Electrical Connection [▶ 13]) or via IO-Link.

The activated working frequency enables another sensor for which this setting is deactivated to be operated in the immediate vicinity without the sensors interfering with each other.

### 6.1.2.5 Using Counter Functions

The counter functions can be parameterized via IO-Link and read out via the "Counter Output Status". To do so, the Config must be switched to the desired mode. If an event is to be parameterized on switching output A2 in relation to the counter functions (Compare mode 1 to 3 and Overflow/underflow mode), the input of pin 2 must be set to output 2 "Counter" and to the desired output function, such as PNP, NPN or push-pull.

### Terminology

| Signal:                     | Is present if an object has been detected                                      |
|-----------------------------|--|
| Counter:                    | Counter that counts if a signal is present                                     |
| Counter Compare Value:      | Configurable value at which an event occurs when it is reached                 |
| Counter Max Value (Period): | Configurable value that specifies the period length in relation to the counter |
| Perioden Counter:           | Indicates the number of periods  |
| Counter Output Status:      | Indicates the switching behavior of the counter                                |

#### **Configurable Counter Modes**

- Only counts
- Compare mode 1
- Compare mode 2
- Compare mode 3
- Overflow/underflow mode

Counting can be up or down in all modes.

#### **Only counts**

In this mode, the device counts the detected objects. Figures 1 and 2 show an example with a "Counter Max Value (Period)" of 5.

| Signal           |   |   |   |   | <u>\</u> |    |     |   |          |
|------------------|---|---|---|---|----------|----|-----|---|----------|
| Counter          | 0 | X | 1 | X | 2        | )3 | χ 4 | 5 | 0 1      |
| Perioden Counter |   |   |   |   |          | 0  |     |   | <u>1</u> |
| Output-Status    |   |   |   |   |          |    |     |   |          |

Illustration 1: Only counts function - counting up

| Signal           |   |     |    |     |   |   |       |   |
|------------------|---|-----|----|-----|---|---|-------|---|
| Counter          | 0 | χ 5 | χ4 | ) з | 2 | 1 | ( 0 ) | 5 |
| Perioden Counter | 0 | χ   |    | 1   |   |   | 2     |   |
| Output-Status    |   |     |    |     |   |   |       |   |

Illustration 2: Only counts function - counting down

#### Compare mode 1

In this mode, the "Counter Output" is switched when the comparison value is reached. If the set period value is reached, this value is maintained, and the "Counter Output" switches back to false. Figures 3 and 4 show the "Compare Mode 1" function with a "Counter Compare Value" of 3 and a "Counter Max Value (Period)" of 5.

| Signal           |   |   | <u> </u> |   |   | <u></u> | \ | <u></u>  | <b>\</b> | <u></u> |   |    |   |   | \ |    | <u> </u> |   | <b>\</b> |          |   |
|------------------|---|---|----------|---|---|---------|---|----------|----------|---------|---|----|---|---|---|----|----------|---|----------|----------|---|
| Counter          | 0 | X | 1        | ) | 2 | X       | 3 | <u>)</u> | 4        | X       | 5 | _X | 0 | χ | 1 | _X | 2        | X | 3        | <u>)</u> | 4 |
| Perioden Counter |   |   |          |   |   | 0       |   |          |          |         |   |    |   |   |   |    | 1        |   |          |          |   |
| Output-Status    |   |   |          |   |   |         |   | 1        |          |         |   |    |   |   |   |    |          |   |          | -        |   |

Illustration 3: Compare mode 1 function - counting up

| Signal           |   |     |     |            | $\frown$ |   |   |   |    |     |   |
|------------------|---|-----|-----|------------|----------|---|---|---|----|-----|---|
| Counter          | 0 | ) 5 | χ 4 | <u>Х з</u> | 2        | 1 | 0 | 5 | χ4 | ) 3 | 2 |
| Perioden Counter | 0 | )   |     |            | 1        |   |   | X | 2  |     |   |
| Output-Status    |   |     |     |            | <u> </u> |   |   |   |    |     |   |

Illustration 4: Compare mode 1 function - counting down

#### Compare mode 2

As soon as the set comparison value is reached, the "Counter Output Status" is switched until the end of the period is reached. Figures 5 and 6 explain the "Compare mode 2" with a "Counter Compare Value" of 3 and a "Counter Max Value (Period)" of 5.

| Signal           |   |     |   |    |    |     |    |    |   |     |     |
|------------------|---|-----|---|----|----|-----|----|----|---|-----|-----|
| Counter          | 0 | X 1 | 2 | ХЗ | χ4 | χ 5 | 0  | χ1 | 2 | ) з | ) 4 |
| Perioden Counter |   |     |   | 0  |    |     | () |    | 1 |     |     |
| Output-Status    |   |     |   |    |    |     |    |    |   |     |     |

Illustration 5: Compare mode 2 function - counting up

| Signal           |   |     |   |     |   |   |   |    |    |    |   |
|------------------|---|-----|---|-----|---|---|---|----|----|----|---|
| Counter          | 0 | χ 5 | 4 | X 3 | 2 | 1 | 0 | 5  | χ4 | χ3 | 2 |
| Perioden Counter | 0 | χ   |   |     | 1 |   |   | () | 2  |    |   |
| Output-Status    |   |     |   |     |   |   |   |    |    |    |   |

Illustration 6: Compare mode 2 function - counting down

#### Compare mode 3

In this mode, the "Counter Output Status" is switched when the comparison value is reached. If the set period value is reached, this value is maintained, and the "Counter Output Status" switches back to false. Figures 7 and 8 show the function with a "Counter Compare Value" of 3 and a "Counter Max Value (Period)" of 5.

| Signal           |   |   |   |  |   | $\int$ |   |   |   |   | $\int$ |  | <u></u> |   |  |  | $\int$ |  |
|------------------|---|---|---|--|---|--------|---|---|---|---|--------|--|---------|---|--|--|--------|--|
| Counter          | 0 | X | 1 |  | 2 | )      | 3 | X | 4 |   |        |  |         | 5 |  |  |        |  |
| Perioden Counter |   |   |   |  |   |        |   |   |   | 0 |        |  |         |   |  |  |        |  |
| Output-Status    |   |   |   |  |   | $\int$ |   |   |   |   |        |  |         |   |  |  |        |  |

Illustration 7: Compare mode 3 function - counting up

Please note: For this function, a value must already be set on the counter when counting down.

| Signal           |   |  |   | <u></u> |   |  |   | 5 |   | <u></u> |   |   |   | $\frown$ |   |   |  | <u></u> |  |  |
|------------------|---|--|---|---------|---|--|---|---|---|---------|---|---|---|----------|---|---|--|---------|--|--|
| Counter          | 5 |  | 4 | )       | 3 |  | 2 |   | 1 | )       |   |   | _ |          | ( | D |  |         |  |  |
| Perioden Counter |   |  |   |         |   |  |   |   |   |         | 0 | _ |   |          |   |   |  |         |  |  |
| Output-Status    |   |  |   | $\int$  |   |  |   |   |   |         |   |   |   |          |   |   |  |         |  |  |

Illustration 8: Compare mode 3 function - counting down

Additionally, in this mode the Counter can be reset by the "One Pulse Status" ("Reset or no event"). A reading can also indicate whether the comparison value has already been reached ("Event detected").

#### Overflow/underflow mode

With this setting, the "Counter Output Status" is always switched if the period end is exceeded or fallen short of. Figures 9 and 10 show the function with a "Counter Compare Value" of 3 and a "Counter Max Value (Period)" of 5.

| Signal           |   |   |     |   |     |   |     |   |   |   |          |
|------------------|---|---|-----|---|-----|---|-----|---|---|---|----------|
| Counter          | 3 | 4 | ( 5 | 0 | ( 1 | 2 | ) 3 | 4 | 5 | 0 | <u>1</u> |
| Perioden Counter |   | 0 |     | X |     |   | 1   |   |   | 2 |          |
| Output-Status    |   |   |     |   |     |   |     |   |   |   | \        |

Illustration 9: Overflow/underflow mode function - counting up

| Signal           |   | $\square$ |   | Γ |   |   | $\square$ | 1 |   |   | 1 |   | $\square$ | 1 |   |   | 7 |   |          |   |   |          |   |   |   |   | Γ        |   |
|------------------|---|-----------|---|---|---|---|-----------|---|---|---|---|---|-----------|---|---|---|---|---|----------|---|---|----------|---|---|---|---|----------|---|
|                  | 0 | ~         | - |   |   | _ | ~         |   | - | ~ |   | _ | ~         | - | - | ~ |   | - | <u> </u> | - | - | <u> </u> | - | - |   | - | <u> </u> | - |
| Counter          | 0 | ٨         | 5 |   | 4 | - | λ         | 3 | - | ٨ | 2 | - | ٨         | 1 | - | λ | 0 |   | <u>ا</u> | 5 | - | <u>ا</u> | 4 | - | λ | 3 |          | 2 |
| Perioden Counter | 0 | χ         |   |   |   |   |           |   |   | 1 |   |   |           |   |   |   |   |   |          |   |   |          |   | 2 |   |   |          |   |
| Output-Status    |   |           |   |   |   |   |           |   |   |   |   |   |           |   |   |   |   |   |          |   | - |          |   |   |   |   |          |   |

Illustration 10: Overflow/underflow mode function - counting down

## 6.2 LED Symbols

| Setup display | Switching status indicator/supply voltage in-<br>dicator | Cause  |
|---------------|--|--|
| ✓ Green*      | 🔆 Blue   | No object present yet  |
| ✓ Green**     | 🔆 Blue   | Object was not reliably detected   |
| 🔆 Green       | 🔆 Blue   | Object was reliably detected   |
| ° Green       | 🔆 Blue   | Object was not detected  |
| -             | 🐔 Red  | Hanger not closed  |
| -             | 🔆 Red  | The device has an error.   |
|               |  | Information on how to remedy the<br>error can be found in the trou-<br>bleshooting section           |
| 🔆 Green       | ✤ Yellow   | Switching output active  |
| -             | * Blue**   | Device has been set to factory set-<br>tings/alternative frequency switch-<br>ing has been activated |

Not lit up

🛠 Flashing

- ✤ Permanently lit up
- \* Flashing behavior: 1 Hz 50 ms On to 950 ms Off
- \*\* Flashing behavior: 1 Hz 500 ms On to 500 ms Off

# 7 Setup via IO-Link

Process and parameter data can be found in the interface protocol at: www.wenglor.com - Products - Enter the desired product number as a search term, then click on "Downloads" on the product page.

#### **Process Data:**

- Counter
- Object size
- Object width (how long the object was detected)
- Error indicator
- Warning
- Switching status A1
- Switching status A2

#### **Parameter Data:**

- Potentiometer lock
- Parametrization of sensitivity
- Parametrization of pulse length
- Output function A1
- Output function A2
- Alternative frequency

# **Maintenance Instructions**



8

## NOTICE

This wenglor sensor is maintenance-free.

Cleaning and inspection of the plug connections at regular intervals are advisable. Do not clean the sensor with solvents or cleaning agents that could damage the product. The product must be protected against contamination during initial start-up.

# 9 Proper Disposal

wenglor sensoric GmbH does not accept the return of unusable or irreparable products. Respectively valid national waste disposal regulations apply to product disposal.

# 10 Declarations of Conformity

Declarations of conformity can be found on our website at www.wenglor.com in the product's separate download area.