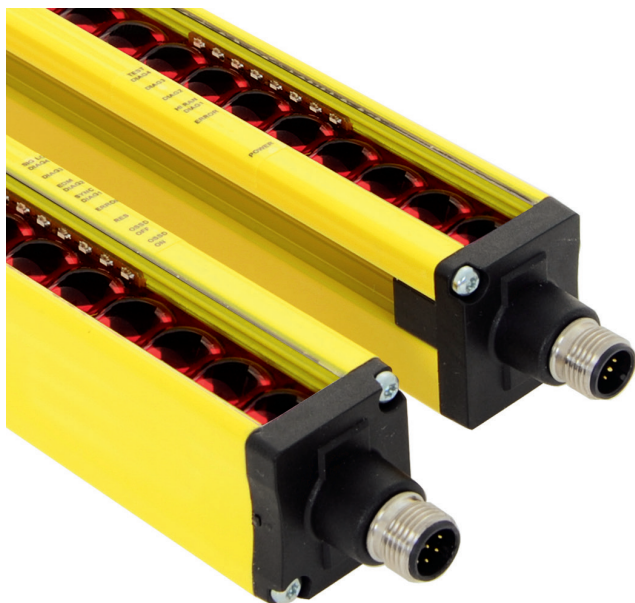


# SEMG452-SEMG482

Type 4 Safety Light Curtain



## Operating Instructions

Translation of the Original Operating Instruction  
Subject to change without notice  
Available as PDF version only  
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# 1. General

## 1.1 Information Concerning these Instructions

- These instructions are valid for the following products: SEMG4xx: Safety Light Curtain sales set consisting of emitter and receiver, SEMG5xx: Safety Light Curtain emitter, SEMG6xx: Safety Light Curtain receiver.
- They make it possible to use the product safely and efficiently.
- These instructions are an integral part of the product and must be kept on hand for the entire duration of its service life.
- Local accident prevention regulations and national work safety regulations must be complied with as well.



### NOTE:

The operating instructions must be read carefully before using the product and must be kept on hand for later reference.

## 1.2 Explanations of Symbols

- Safety precautions and warnings are emphasized by means of symbols and attention-getting words.
- Safe use of the product is only possible if these safety precautions and warnings are adhered to.

The safety precautions and warnings are laid out in accordance with the following principle:



### ATTENTION-GETTING WORD!

#### Type and Source of Danger!

Possible consequences in the event that the hazard is disregarded.

- Measures for averting the hazard.

The meanings of the attention-getting words, as well as the scope of the associated hazards, are listed below:



### DANGER!

This word indicates a hazard with a high degree of risk which, if not avoided, results in death or severe injury.



### WARNING!

This word indicates a hazard with a medium degree of risk which, if not avoided, may result in death or severe injury.



### CAUTION!

This word indicates a hazard with a low degree of risk which, if not avoided, may result in minor or moderate injury.



### ATTENTION!

This word draws attention to a potentially hazardous situation which, if not avoided, may result in property damage.



### NOTE!

A note draws attention to useful tips and suggestions, as well as information regarding efficient, error-free use.

---

## LED Symbols

Descriptions of statuses of diagnostics LEDs



LED is lit up continuously.



The LED can have any status (lit up or off).



LED blinks.



LED is off.

---

## 1.3 List of Abbreviations

Abbreviation	Meaning
ESPE	Electro-sensitive protective equipment
SFH	Safety field height
EDM	External device monitoring = contactor monitoring
RES	Restart inhibit
OSSD	Output signal switching device

## 1.4 Limitation of Liability

- The product has been developed in consideration of the current state-of-the-art and applicable standards and guidelines. Subject to change without notice.
- wenglor excludes all liability in the event of:
  - Non-compliance with the instructions
  - Use of the product for purposes other than those intended
  - Use by untrained personnel
  - Use of unapproved replacement parts
  - Unapproved modification of products
  - These operating instructions do not imply any guarantee from wenglor with regard to the described procedures or specific product characteristics.
  - wenglor assumes no liability for printing errors or other inaccuracies contained in these operating instructions, unless wenglor was verifiably aware of such errors at the point in time at which the operating instructions were prepared.

## 1.5 Copyrights

- The contents of these instructions are protected by copyright law.
- All rights are reserved by wenglor.
- Commercial reproduction or any other commercial use of the provided content and information, in particular graphics and images, is not permitted without previous written consent from wenglor.

## 2. For Your Safety

### 2.1 Use for Intended Purpose

The product is based on the following functional principle:

#### Safety Light Curtain

The Safety Light Curtain monitors the safety field between the emitter and the receiver. If the safety field is interrupted by an obstruction, a switching command is triggered. This switching command either prevents initialization of a hazardous machine motion, or stops an action which has already been started.

#### Use of the Light Curtain is only permissible if:

- Hazardous motion can be stopped by electrical means using the light curtain's safety output
- Adequate detection of possible obstruction is assured with existing resolution
- Use of a type 4 Light Curtain with performance level PL e is permissible

#### This product can be used in the following industry sectors:

- |                                   |                            |
|-----------------------------------|----------------------------|
| • Special machinery manufacturing | • Electronics industry     |
| • Heavy machinery manufacturing   | • Glass industry           |
| • Logistics                       | • Steel industry           |
| • Automotive industry             | • Printing industry        |
| • Food industry                   | • Aviation industry        |
| • Packaging industry              | • Construction industry    |
| • Pharmaceuticals industry        | • Chemicals industry       |
| • Clothing industry               | • Agriculture industry     |
| • Plastics industry               | • Alternative energy       |
| • Woodworking industry            | • Raw materials extraction |
| • Consumer goods industry         | • Other                    |
| • Paper industry                  |                            |

### 2.2 Use for Other than the Intended Purpose

- The product is not suitable for use in potentially explosive atmospheres.
- Only accessories supplied or approved by wenglor may be used with the product.



---

#### **DANGER!**

**Risk of personal injury or property damage in case of use for other than the intended purpose!**

Use for other than the intended purpose may lead to hazardous situations.

- Observe instructions regarding use for intended purpose.
-

## 2.3 Personnel Qualifications

- Suitable technical training is a prerequisite.
- In-house electronics training is required.
- Technical knowledge and experience concerning use of the guard is required in order to assure correct evaluation of the safe working status during assembly, initial start-up and electrical installation.
- Trained personnel must have uninterrupted access to the operating instructions.



### CAUTION!

**Risk of personal injury or property damage in case of incorrect initial start-up and maintenance!**

Personal injury and damage to equipment may occur.

- Adequate training and qualification of personnel

## 2.4 Modification of Products



### NOTE!

Modification of the product is impermissible.

Non-observance may result in loss of the CE marking and the guarantee may be rendered null and void.

## 2.5 General Safety Precautions



### NOTE!

- These instructions are an integral part of the product and must be kept on hand for the entire duration of its service life.
- Read the operating instructions carefully before using the product.
- Protect the sensor against contamination and mechanical influences.
- Additional measures may be necessary in order to assure that the ESPE does not fail in a dangerous fashion due to other types of light which are used in a special application (e.g. emission due to welding sparks or the effects of stroboscope lights).

## 2.6 Approvals and protection class



### 3. Technical Data

Order No.	Emitter: SEMG571–SEMG582 Receiver: SEMG671–SEMG682	Emitter: SEMG671–SEMG682 Receiver: SEMG652–SEMG662
Optical Data		
Range	0.2...6 m	0.25...14 m
Safety field height	250...1811 mm	326...1827 mm
Resolution	14 mm	30 mm
Aperture angle	± 2.5°	
Emitter wave length	Typically 630 nm	
Coated optics	Yes	
Resistance to extraneous light	10,000 lux	
Electrical Data		
Supply power	19.2 to 28.8 V DC (SELV, PELV power pack), it must be possible to bridge power failures of 20 ms or more (EN 60204-1) For US and Canada: Device to be supplied by a certified Class 2 power supply that complies with the requirements according NEC and CEC.	
Protection class	III (SELV/PELV)	
Fusing of supply voltage, inputs	Max. 2 A	
Power consumption, receiver (operating voltage = 24 V)	≤ 200 mA (without load)	
Power consumption, emitter (operating voltage = 24 V)	≤ 100 mA	
Internal fuse	2 A	
Temperature range *	SFH ≤ 1061 mm: –25...55 °C SFH > 1061 mm: –5...55 °C	–25...55 °C
Storage temperature *	–25...60 °C	
Relative humidity	≤ 95% (non-condensing)	
Vibration resistance	5 g (10 ... 55 Hz)	
Shock resistance	10 g/16 ms	
Signal output		
Signal output	Semiconductor, PNP	
Number of signal outputs	1	
Signal output switching current	≤ 100 mA	
Signal output voltage drop	≤ 2.5 V	
Safety outputs		
Safety outputs	Semiconductor, PNP	
Number of safety outputs	2	
Safety output switching current	≤ 300 mA	
Safety output leakage current	≤ 2 mA	
Voltage drop at safety output	≤ 2.3 V	
Max. voltage in off state	< 2 V	
Max. capacitive load	≤ 1 µF	
Max. Inductive load	≤ 2.2 H	

\* For operating and storage temperatures down to  $-30^\circ\text{C}$ , see [section 12.7, page 75](#)

Order No.	Emitter: SEMG571–SEMG582 Receiver: SEMG671–SEMG682	Emitter: SEMG671–SEMG682 Receiver: SEMG652–SEMG662
Test pulse width, rate	< 300 μs, typically 20 ms	
Restart time after reach-in	Typically 2 × response time	
Inputs		
Voltage range	–30...30 V DC	
Switching thresholds	LOW: < 5 V, < 2 mA HI: > 11 V, 6...30 mA	
Activation duration	0.1...4 s	
Acknowledgment input		
EDM response/drop-off time	350 ms	
Short-circuit proof	Yes	
Reversed polarity and overload proof	Yes	
Max. cable length	< 35 m/0.25 sq. mm < 50 m/0.34 sq. mm < 72 m/0.50 sq. mm	
Mechanical		
Housing material	Aluminum	
Protection	IP65, IP67	
Emitter connection	4/5-pin M12	
Receiver connection	8-pin M12	
Technical Safety Data		
ESPE type (EN 61496)	4	
Performance level (EN ISO 13849-1:2008)	Cat. 4 PL e	
Safety integrity level (EN 62061)	SIL cl 3	
PFHd	1,6 E-8 1/h	
Service life TM (EN ISO 13849-1:2008)	20 a	
Functions		
Finger protection	Yes	No
Hand protection	No	Yes
Safety mode (Automatic Operation)	Yes	
Restart inhibit	Yes	
Contactors monitoring	Yes	

The following table specifies the tightening torques of the plugs and mounting options in order to assure compliant, error-free operation:

Connection type	Connection tightening torque in Nm
M12	0,4

### 3.1 Response Times

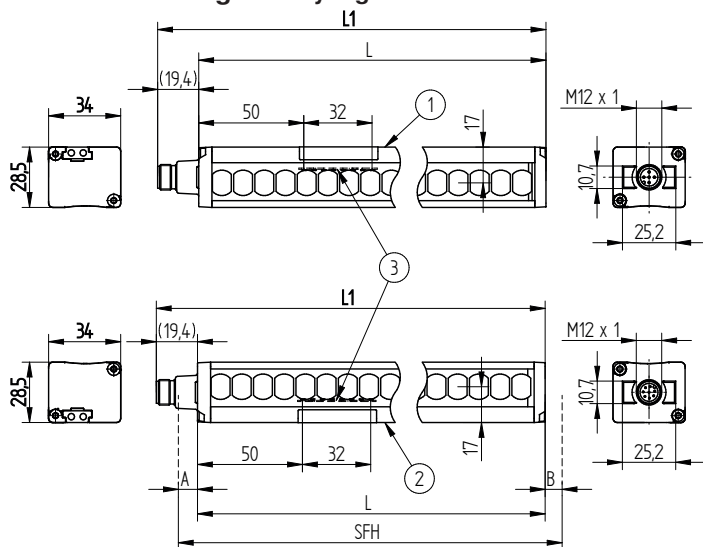
#### Resolution: 14 mm

Order Number	Response Time [ms]
SEMG671	7,6
SEMG672	8,3
SEMG673	9,9
SEMG674	11,6
SEMG675	13,2
SEMG676	14,9
SEMG677	16,5
SEMG678	18,2
SEMG679	19,8
SEMG680	21,5
SEMG681	23,1
SEMG682	24,8

#### Resolution: 30 mm

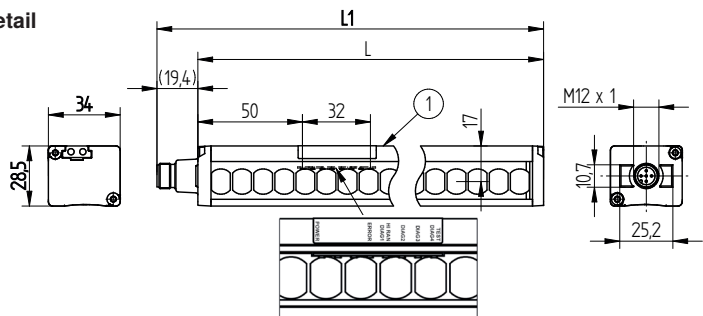
Order Number	Response Time [ms]
SEMG652	6,6
SEMG653	7,5
SEMG654	8,3
SEMG655	9,1
SEMG656	9,9
SEMG657	10,8
SEMG658	11,6
SEMG659	12,4
SEMG660	13,2
SEMG661	14,1
SEMG662	14,9

### 3.2 Dimensional Drawings Safety Light Curtain

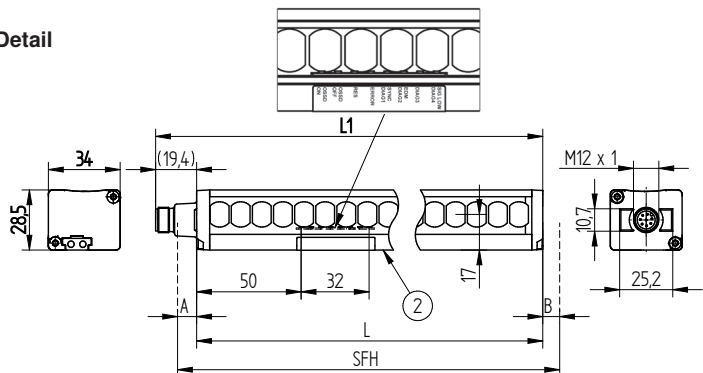


1 = emitter, 2 = receiver, 3 = control panel, SFH = safety field height

### Emitter Detail



### Receiver Detail





**Resolution: 14 mm**

Order Number	SFH (mm)	L (mm)	L1	A (mm)	B (mm)	Max. weight per sensor (kg)
SEMGx71	250	250	269	0	0	0,38
SEMGx72	310	310	330	0	0	0,53
SEMGx73	460	460	480	0	0	0,69
SEMGx74	610	610	630	0	0	0,84
SEMGx75	761	761	780	0	0	0,99
SEMGx76	911	911	930	0	0	1,15
SEMGx77	1061	1061	1080	0	0	1,30
SEMGx78	1211	1211	1230	0	0	1,45
SEMGx79	1361	1361	1380	0	0	1,61
SEMGx80	1511	1511	1531	0	0	1,76
SEMGx81	1661	1661	1681	0	0	1,91
SEMGx82	1811	1811	1831	0	0	2,07

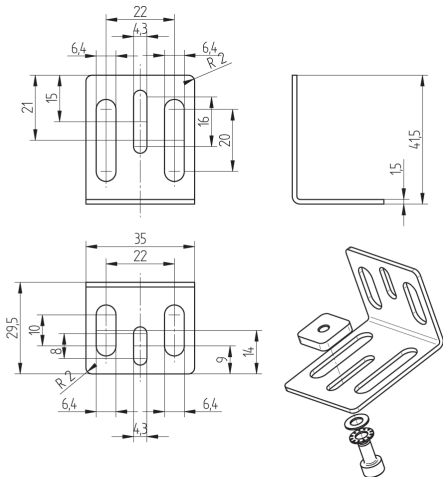
**Resolution: 30 mm**

Order Number	SFH (mm)	L (mm)	L1	A (mm)	B (mm)	Max. weight per sensor (kg)
SEMGx52	326	312	332	14	0	0,53
SEMGx53	486	462	482	14	10	0,69
SEMGx54	626	612	632	14	0	0,84
SEMGx55	787	763	782	14	10	0,99
SEMGx56	927	913	932	14	0	1,15
SEMGx57	1087	1063	1082	14	10	1,30
SEMGx58	1227	1213	1232	14	0	1,45
SEMGx59	1387	1363	1382	14	10	1,61
SEMGx60	1527	1513	1533	14	0	1,76
SEMGx61	1687	1663	1683	14	10	1,91
SEMGx62	1827	1813	1833	14	0	2,07

### 3.3 Housing dimensions, mounting technology

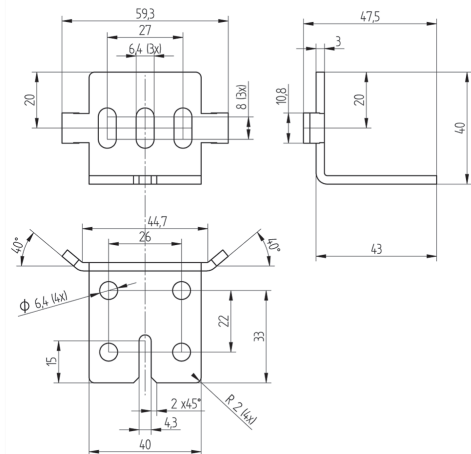
#### ZEMX001 Mounting Bracket

- For wall/profile mounting
- Scope of delivery: 2 pieces
- Including screws, washers and slot nuts



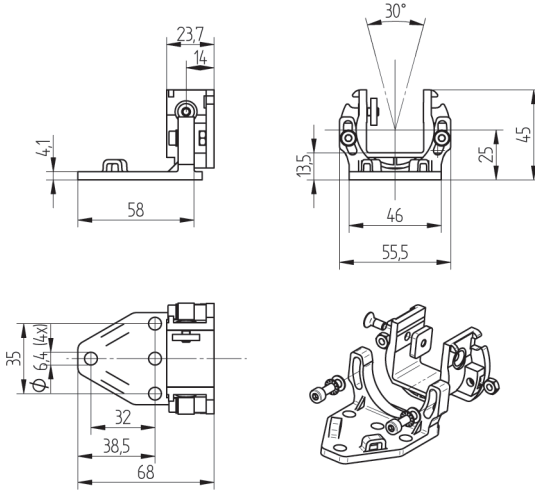
#### ZEMX002 Mounting Bracket

- For mounting in Protection Columns
- Scope of delivery: 2 pieces
- Including screws, washers and slot nuts



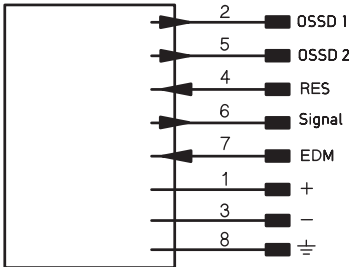
### ZEMZ001 Mounting System

- For wall mounting
- Adjustable
- Scope of delivery: 2 pieces
- Including screws, washers and slot nuts

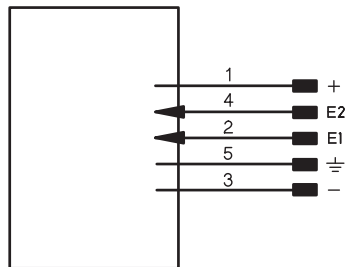


### 3.4 Connection Diagrams

Receiver



Emitter



+	+ supply power
-	0 V supply power
OSSD	Safety output
Signal	Signal output
⏏	Ground
RES	Acknowledgement input
EDM	Contact monitoring
E	Analog or digital input

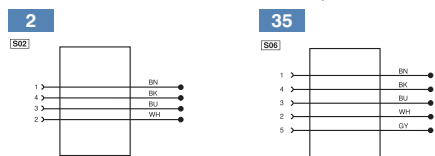
## Legend

+	Supply Voltage +	PT	Platinum measuring resistor	ENaRS422	Encoder A/Ä (TTL)
-	Supply Voltage 0 V	nc	not connected	ENbRS422	Encoder B/B (TTL)
~	Supply Voltage (AC Voltage)	U	Test Input	ENa	Encoder A
A	Switching Output (NO)	Ü	Test Input inverted	ENb	Encoder B
Ä	Switching Output (NC)	W	Trigger Input	AMIN	Digital output MIN
V	Contamination/Error Output (NO)	W-	Ground for the Trigger Input	AMAX	Digital output MAX
Ü	Contamination/Error Output (NC)	O	Analog Output	AOk	Digital output OK
Input (analog or digital)		O-	Ground for the Analog Output	SY in	Synchronization In
T	Teach Input	BZ	Block Discharge	SY OUT	Synchronization OUT
Z	Time Delay (activation)	AWV	Valve Output	0.LT	Brightness output
S	Shielding	a	Valve Control Output +	M	Maintenance
RxD	Interface Receive Path	b	Valve Control Output 0 V	RSV	reserved
TxD	Interface Send Path	SY	Synchronization	Wire Colors according to IEC 60757	
RDY	Ready	SY-	Ground for the Synchronization	BK	Black
GND	Ground	E+	Receiver-Line	BN	Brown
CL	Clock	S+	Emitter-Line	RD	Red
E/A	Output/Input programmable	±	Grounding	OG	Orange
IO-Link		SnR	Switching Distance Reduction	YE	Yellow
PoE	Power over Ethernet	Rx+/-	Ethernet Receive Path	GN	Green
IN	Safety Input	Tx+/-	Ethernet Send Path	BU	Blue
OSSD	Safety Output	Bus	Interfaces-Bus A(+)/B(-)	VT	Violet
Signal	Signal Output	La	Emitted Light disengageable	GY	Grey
BL_D +/-	Ethernet Gigabit bidirect. data line (A-D)	Mag	Magnet activation	WH	White
ENaRS422	Encoder 0-pulse 0-0 (TTL)	RES	Input confirmation	PK	Pink
		EDM	Contactor Monitoring	GNYE	Green/Yellow

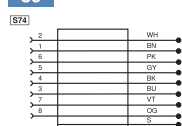
## 3.5 Complementary Products (see catalog)

wenglor offers Connection Technology for field wiring.

Suitable Mounting Technology No.	810	790	820
Suitable Connection Technology No. (emitter, Color code for connection cable)			

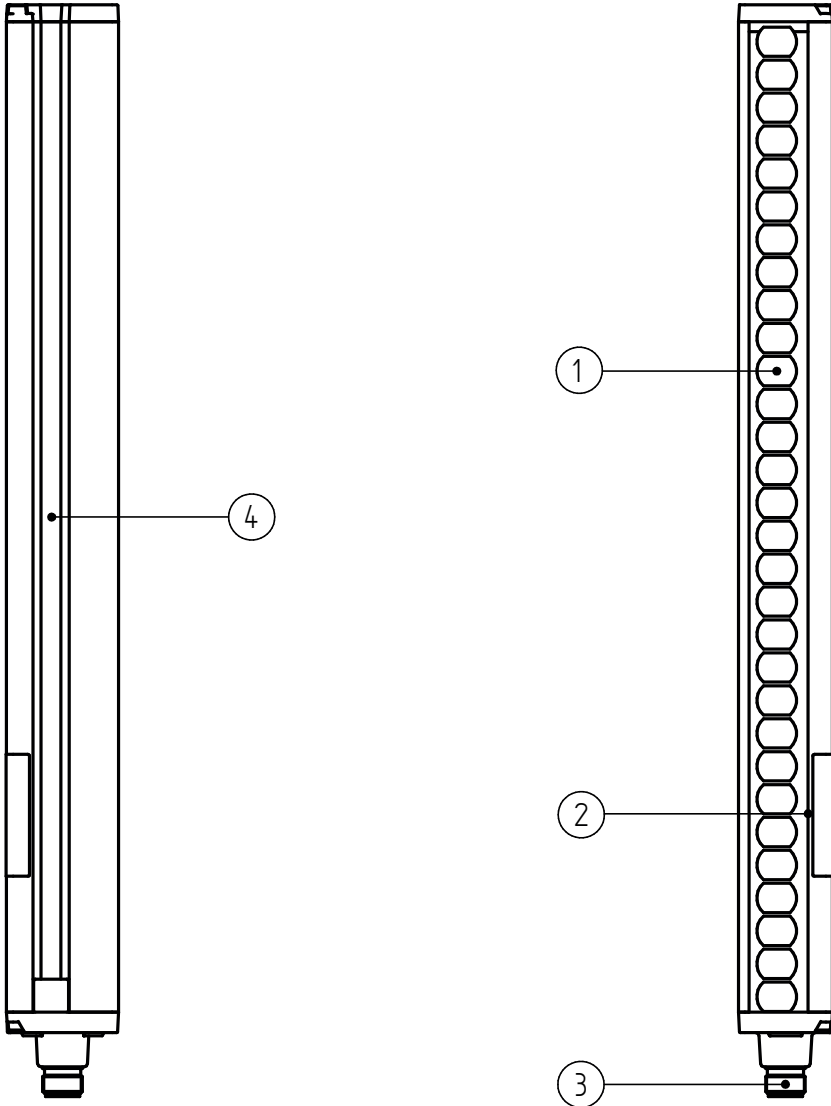


Suitable Connection Technology No. (receiver, Color code for connection cable)
89



Deflection Mirror Z2UG004
Protection Column with Deflection Mirror SZ000EU170NN01
Protection Column with Screening Grid SZ000EG170NN01
Safety Relay SG4-00VA000R2, SR4B3B01S, SR4D3B01S

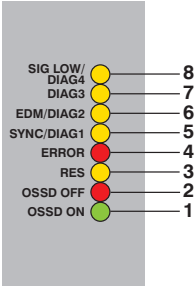
### 3.6 Layout



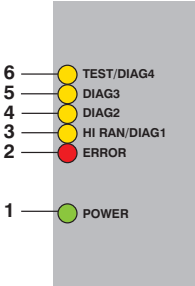
- 1 = optics (safety field)
- 2 = indicator LEDs (control panel)
- 3 = plug connector
- 4 = mounting slot

### 3.7 Control Panel

#### Receiver

	Display	Color	
8	Diagnostics 4/weak signal	YE	 A vertical grey rectangular panel with eight circular LEDs. From top to bottom: yellow (labeled 8), yellow (labeled 7), yellow (labeled 6), yellow (labeled 5), red (labeled 4), yellow (labeled 3), red (labeled 2), and green (labeled 1). To the left of the LEDs, text labels are aligned with their respective numbers: SIG LOW/DIAG4 (8), DIAG3 (7), EDM/DIAG2 (6), SYNC/DIAG1 (5), ERROR (4), RES (3), OSSD OFF (2), and OSSD ON (1). SIG LOW/ DIAG4 DIAG3 EDM/DIAG2 SYNC/DIAG1 ERROR RES OSSD OFF OSSD ON
7	Diagnostics 3	YE	
6	Diagnostics 2/contactor monitoring	YE	
5	Diagnostics 1/ synchronization	YE	
4	Error	RD	
3	Acknowledgment prompt	YE	
2	OSSD off	RD	
1	OSSD on	GN	

#### Emitter

	Display	Color	
6	Diagnostics 4/test	YE	 A vertical grey rectangular panel with six circular LEDs. From top to bottom: yellow (labeled 6), yellow (labeled 5), yellow (labeled 4), yellow (labeled 3), red (labeled 2), and green (labeled 1). To the left of the LEDs, text labels are aligned with their respective numbers: TEST/DIAG4 (6), DIAG3 (5), DIAG2 (4), HI RAN/DIAG1 (3), ERROR (2), and POWER (1). 6 — TEST/DIAG4 5 — DIAG3 4 — DIAG2 3 — HI RAN/DIAG1 2 — ERROR 1 — POWER
5	Diagnostics 3	YE	
4	Diagnostics 2	YE	
3	Diagnose 1/high range	YE	
2	Error	RD	
1	Supply power	GN	

### 3.8 Scope of Delivery

- Emitter and receiver with identical SFH
- Quick start
- Operating Instructions on CD
- Test rod matched to the resolution of the ESPE (Ø 14 mm – ZEMG003/Ø 30 mm – ZEMG004)
- Regular Inspection sticker
- Mounting bracket (ZEMX001)

## 4. Transport and Storage

### 4.1 Transport

Upon receipt of shipment, inspect the goods for damage in transit. In the case of damage, conditionally accept the package and notify the manufacturer of the damage. Then return the device making reference to damage in transit.

### 4.2 Storage

**The following points must be taken into condition with regard to storage:**

- Do not store the product outdoors.
- Store the product in a dry, dust-free place.
- Protect the product against mechanical impacts.
- Protect the product against exposure to direct sunlight.



**ATTENTION:**

**Risk of property damage in case of improper storage!**

The product may be damaged.

- Comply with storage instructions.
-

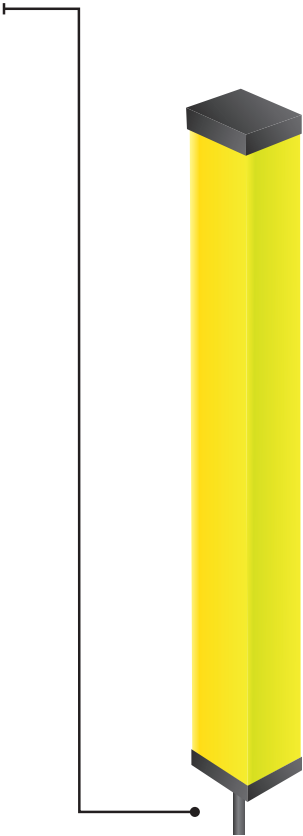
# 5. Installation and Electrical Connection

## 5.1 System Overview

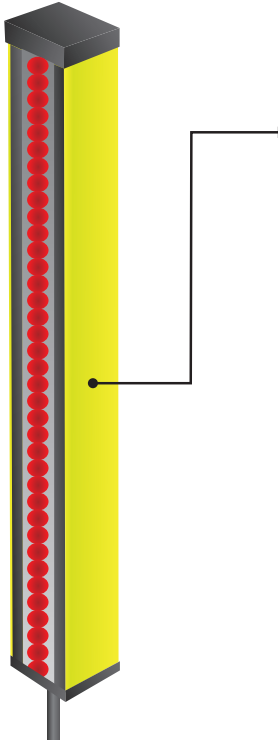
Connector Cables*	
M12, 4-pin to open end (for emitter)	
S23-2M (straight, PVC)	2 m
S23-5M (straight, PVC)	5 m
S23-10M (straight, PVC)	10 m
S29-2M (angled, PVC)	2 m
S29-5M (angled, PVC)	5 m
S29-10M (angled, PVC)	10 m
M12, 5-pin to open end (for emitter)	
ZAS35R501 (straight, PUR)	5 m
M12, 8-pin to open end (for receiver)	
ZAS89R501 (straight, PUR)	5 m
ZAS89R601 (straight, PUR)	10 m
ZAS89R502 (angled, PUR)	5 m
ZAS89R602 (angled, PUR)	10 m

\* Further suitable connection equipment can be found on our website at [www.wenglor.com](http://www.wenglor.com)

Safety Relays
SG4-00VA000R2
SR4B3B01S
SR4D3B01S







### Mounting Technology\*

Mounting bracket ZEMX001

Mounting bracket ZEMX002

Mounting system ZEMZ001

\* Further suitable mounting technology can be found on our website at [www.wenglor.com](http://www.wenglor.com)

### Safety Columns \*\*

Z2SS001 (with protective disc)	930 mm
Z2SS002 (with protective disc)	1380 mm
Z2SS003 (with protective disc)	1830 mm
Z2SU001 (with path-folding mirror)	930 mm
Z2SU002 (with path-folding mirror)	1380 mm
Z2SU003 (with path-folding mirror)	1830 mm

\*\* Further suitable protection columns can be found on our website at [www.wenglor.com](http://www.wenglor.com)

### Path-Folding Mirrors

Z2UG001	80 mm
Z2UG002	750 mm
Z2UG003	1350 mm
Z2UG004	1900 mm

## 5.2 Installation

- Protect the product from contamination during installation.
- Observe all applicable electrical and mechanical regulations, standards, and safety rules.
- Protect the product against mechanical influences.
- Make sure that the sensor is mounted in a mechanically secure fashion.
- Specified torque values must be complied with (see section "3. Technical Data" on page 9).



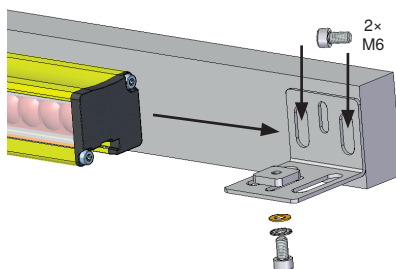
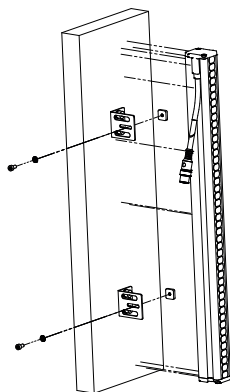
### ATTENTION:

#### Risk of property damage in case of improper installation!

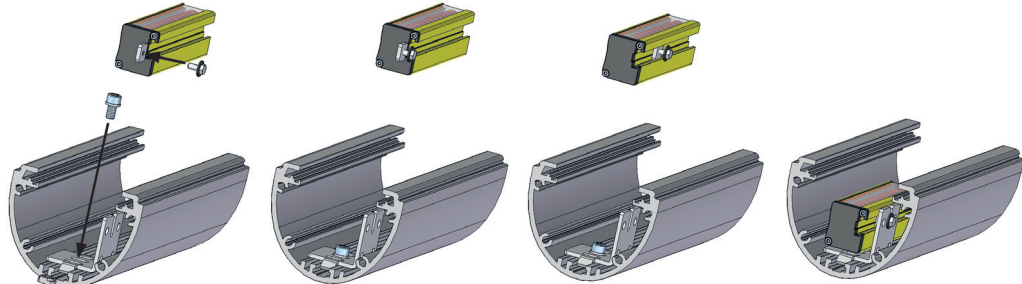
The product may be damaged.

- Comply with installation instructions.

### 5.2.1 Installation with ZEMX001 Mounting Bracket

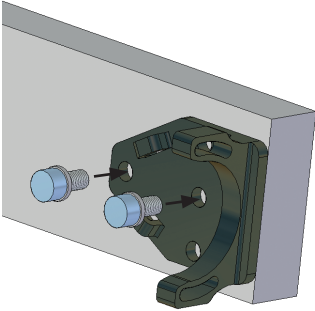


### 5.2.2 Installation with ZEMX002 Mounting Bracket

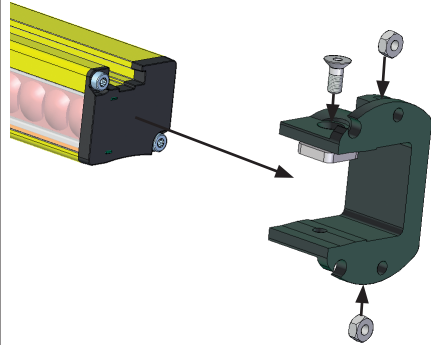


## 5.2.3 Installation with ZEMZ001 Mounting System

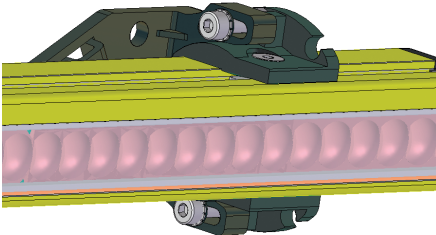
### 1. Install the wall mounting.



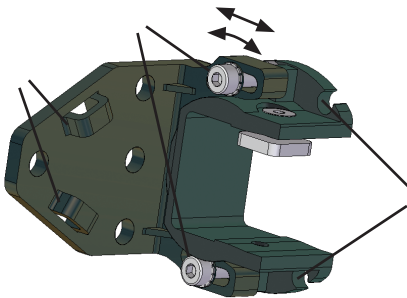
### 2. Attach the profile mounting.



### 3. Join the wall and profile mountings to each other.



### 4. Alignment



#### 1 Securing the Cable

- The cable can be secured with cable ties.

#### 2 Aligning the ESPE

- Slightly loosen the screws between the wall and profile mountings.
- Align the ESPE.
- Turn the ESPE in the axial direction.
- Adjust ESPE inclination.

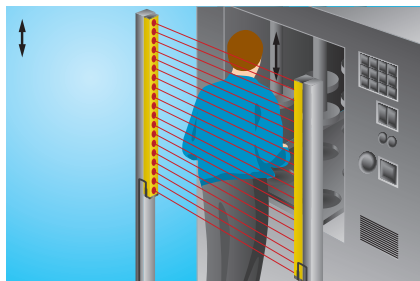
#### 3 Securing the Cable

- The cable can be snapped into the openings.

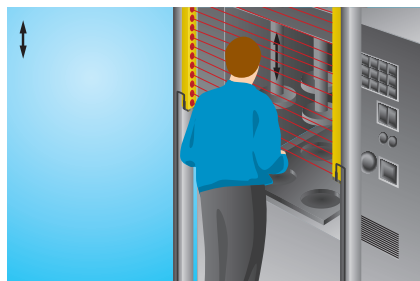
### 5.3 Securing the Danger Zone

- The danger zone must be secured either by means of the ESPE alone, or by means of the ESPE in combination with additional mechanical safety devices.
- Reaching around, over and/or under the safety field must be prevented.
- It must be impossible to approach the point of danger without passing through the safety field of the ESPE.
- The safety field is located between the point at which light is emitted at the emitter and the point at which light is received at the receiver.
- SFH of the respective ESPE: (see section “3.2 Dimensional Drawings Safety Light Curtain” on page 12)

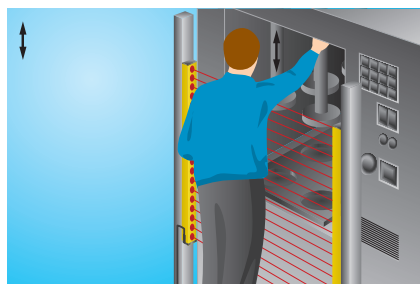
#### Incorrect



Side-Stepping

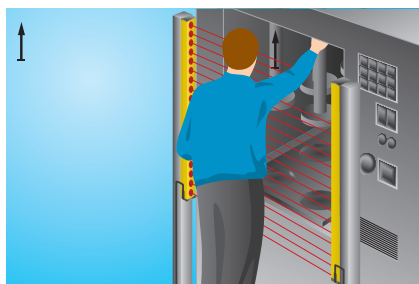
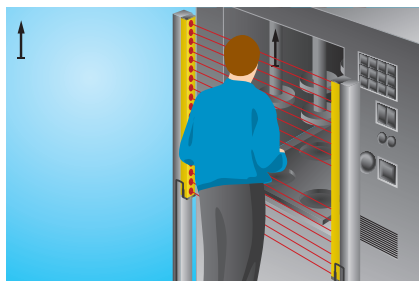
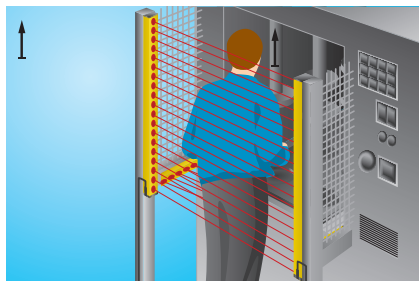


Reaching Under



Reaching Over

#### Correct



## 5.4 Safety Clearance



EN ISO 13855 + EN ISO 13857

### [abc]

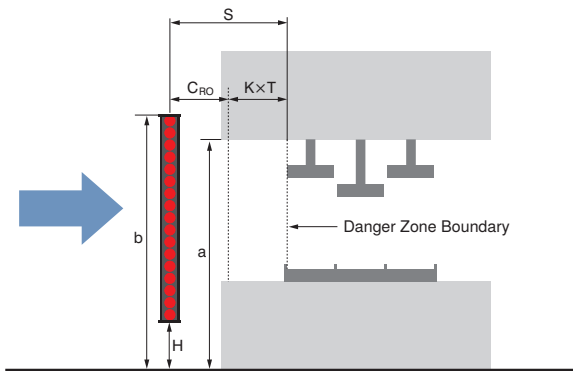
- Safety clearance is the minimum distance between the safety field of the ESPE and the danger zone.
- Safety clearance must be adhered to, in order to assure that the danger zone cannot be reached before hazardous motion is fully stopped.



$$S = (K \times T) + C_{RT} \text{ resp. } S = K \times (t_1 + t_2) + C_{RT}$$

$S$ [mm]	= safety clearance measured from the danger zone to the safety field
$K$ [mm/s]	= approach speed
$T$ [s]	= total response time ( $t_1 + t_2$ )
$t_1$ [s]	= ESPE response time
$t_2$ [s]	= machine or process overtravel time (overtravel time is specified in the machine's documentation, or must be ascertained by means of measurement)
$C_{RT}$ [mm]	= additional clearance depending upon resolution $d$ with reference to reaching through the ESPE
$C_{RO}$ [mm]	= additional clearance with reference to reaching over an ESPE
$d$ [mm]	= resolution of the ESPE
$H$ [mm]	= reference height, height of the safety field above the floor
$a$ [mm]	= height of the danger zone
$b$ [mm]	= height of the top edge of the safety field

### 5.4.1 Safety Clearance for Vertical Approach to the Safety Field



Observe reference height  $H$ .

$H \leq 300$  mm  $\rightarrow$  avoid danger of undetected access underneath the safety field.

$H < 200$  mm  $\rightarrow$  avoid danger of undetected access by children underneath the safety field.

Height of the uppermost beam  $\geq 900$  mm  $\rightarrow$  prevent danger of stepping over the safety field.



Resolution d	Margin $C_{RT}$	Approach speed K	Safety clearance S	Note
≥ 14 mm	8 × (d – 14 mm) C = 0 mm (at d = 14 mm)	2000 mm/s (where S ≤ 500 mm)	S = (2000 mm/s × T) + 8 × (d – 14 mm)	S may not be ≤ 100 mm
		1600 mm/s (where S > 500 mm)	S = (1600 mm/s × T) + 8 × (d – 14 mm)	
≥ 30 mm	8 × (d – 14 mm) C = 128 mm (at d = 30 mm)	2000 mm/s (where S ≤ 500 mm)	S = (2000 mm/s × T) + 8 × (d – 14 mm)	S may not be ≤ 150 mm
		1600 mm/s (where S > 500 mm)	S = (1600 mm/s × T) + 8 × (d – 14 mm)	

### Prevent Reaching Over the Safety Field

Height of the danger zone a (mm)	Additional horizontal clearance $C_{Ro}$ to the danger zone [mm]											
2600	0	0	0	0	0	0	0	0	0	0	0	0
2500	400	400	350	300	300	300	300	300	250	150	100	0
2400	550	550	550	500	450	450	400	400	300	250	100	0
2200	800	750	750	700	650	650	600	550	400	250	0	0
2000	950	950	850	850	800	750	700	550	400	0	0	0
1800	1100	1100	950	950	850	800	750	550	0	0	0	0
1600	1150	1150	1100	1000	900	850	750	450	0	0	0	0
1400	1200	1200	1100	1000	900	850	650	0	0	0	0	0
1200	1200	1200	1100	1000	850	800	0	0	0	0	0	0
1000	1200	1150	1050	950	750	700	0	0	0	0	0	0
800	1150	1050	950	800	500	450	0	0	0	0	0	0
600	1050	950	750	550	0	0	0	0	0	0	0	0
400	900	700	0	0	0	0	0	0	0	0	0	0
200	600	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0
	Height b, top edge of the safety field (mm)											
	900	1000	1100	1200	1300	1400	1600	1800	2000	2200	2400	2600

### NOTE!



- Safety field top-edge heights of less than 900 mm do not provide adequate protection against stepping around or over the safety field.
- Safety field bottom-edge heights of greater than 300 mm do not provide adequate protection against crawling under the safety field.



ESPE response time  $t_1$  = 10 ms  
 ESPE resolution  $d$  = 30 mm  
 Machine overtravel time  $t_2$  = 250 ms  
 Danger zone height  $a$  = 800 mm

**Step 1:** Calculate safety clearance for crawling under.

$$S_{RT} = 2000 \text{ mm/s} \times (t_1 + t_2) + C_{RT}$$

$$S_{RT} = 2000 \text{ mm/s} \times (0.25 \text{ s} + 0.01 \text{ s}) + 8 (30 \text{ mm} - 14 \text{ mm})$$

$$S_{RT} = 648 \text{ mm}$$

$$S_{RT} > 500 \text{ mm, and thus new calculation with } K = 1600 \text{ mm/s}$$

$$S_{RT} = 1600 \text{ mm/s} \times (0.25 \text{ s} + 0.01 \text{ s}) + 8 (30 \text{ mm} - 14 \text{ mm})$$

$$S_{RT} = 544 \text{ mm}$$

**Step 2:** Determine additional clearance  $C_{RO}$ .

$$S = (K \times T) + C$$

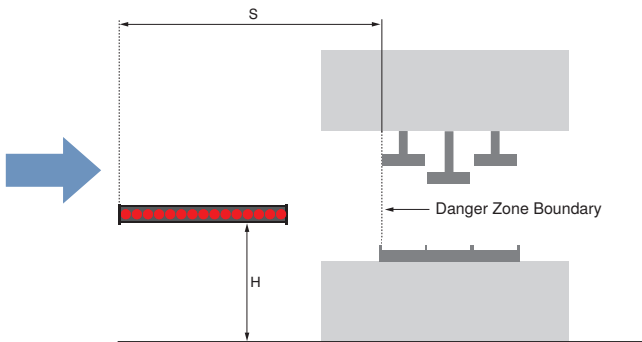
Equating  $S_{R0} = S_{RT}$  results in  $C_{RO} = C_{RT} = 128 \text{ mm}$

Find  $a = 800 \text{ mm}$  in the table titled "Prevent Reaching Over the Safety Field" and take the next smaller value of  $C_{RO} = 0 \text{ mm}$ .

**Step 3:** Determine the height of the top edge of the ESPE safety field  $b$ .

Take the corresponding value from the table:  $b = 1600 \text{ mm}$ .

## 5.4.2 Safety Clearance for horizontal approach to the Safety Field





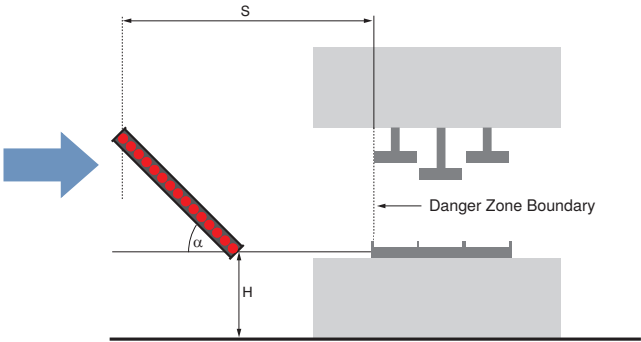
Reference height H	$200\text{ mm} < H < 1000\text{ mm}$	
Minimum height $H_{\min}$	$H_{\min} = 15 \times (d - 50\text{ mm})$	$H \geq 0\text{ mm}$
Margin C	$C = 1200\text{ mm} - 0.4 \times H$ $C_{\min} \geq 850\text{ mm}$	
Approach speed K	$1600\text{ mm/s}$	
Resulting resolution d	$d = (H/15) + 50\text{ mm}$	Required resolution must be calculated for the specified height.
Safety clearance S	$S = (1600\text{ mm/s} \times T) + (1200\text{ mm} - 0.4 \times H)$	S may not be $\leq 850\text{ mm}$ . S is between the danger zone and the furthest beam of the sensor.

**Example:**

- ESPE response time = 10 ms
- ESPE resolution = 14 mm
- Machine over-travel time = 330 ms
- Reference height = 500 mm  
 $S = 1600\text{ mm/s} \times (0.33\text{ s} + 0.01\text{ s}) + 1200\text{ mm} - (0.4 \times 500\text{ mm})$   
 $S = 1544\text{ mm}$
- Resultant resolution  $d = (500\text{ mm}/15) + 50\text{ mm} = 83.3\text{ mm}$

**5.4.3 Safety Clearance for Angular Approach to the Safety Field**

For applications where  $5^\circ < \alpha < 85^\circ$





	$\alpha > 30^\circ$	$\alpha < 30^\circ$
Calculation based on	Vertical approach	Horizontal approach
Safety clearance refers to	Distance between the point of danger and the closest light beam	Distance between the point of danger and the furthest light beam
Note		The height of the furthest light beam may not be $\leq 1000$ mm. The following applies to the closest light beam: $H = 15 \times (d - 50 \text{ mm})$ and $d = H/15 + 50 \text{ mm}$

### 5.5 Clearance from Reflective Surfaces



**NOTE!**

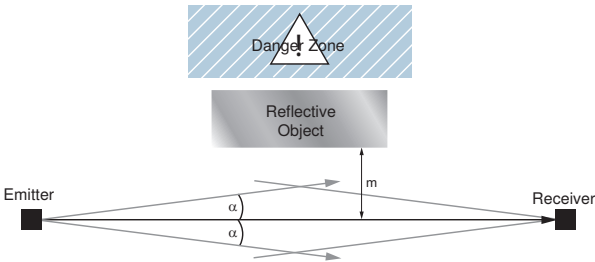
- Reflective surfaces located within the aperture angle between the emitter and the receiver may counteract the system's safety function.
- Minimum clearance (m) from reflective surfaces to the optical axis must be adhered to.



IEC 61496-2

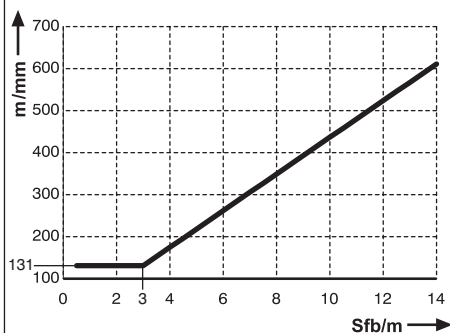


$m = \tan \alpha \times \text{safety field width}$



$$\alpha = 2,5^\circ$$

$$m = \tan 2.5^\circ \times \text{distance from emitter to receiver}$$



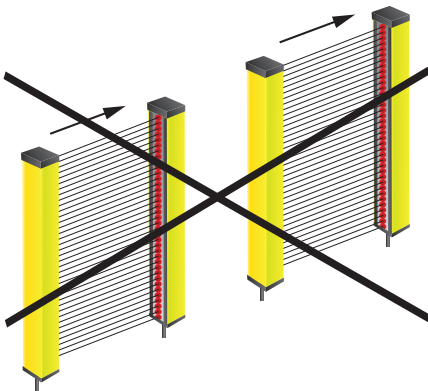
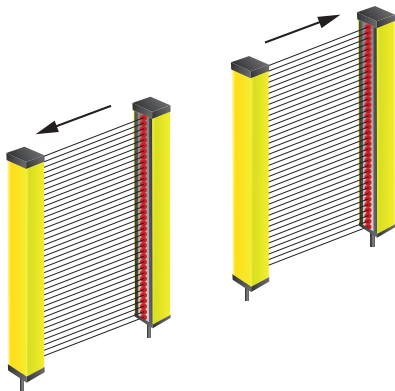
m/mm = minimum clearance [mm]

Sfb/m = distance from emitter to receiver [m]

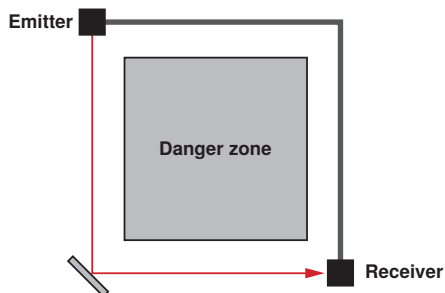
## 5.6 Multiple Systems

### NOTE!

- Reciprocal influence of neighboring ESPEs may counteract the system's safety function.
- Only the light from the associated emitter may strike the receiver.
- Measures for the prevention of mutual influence in multiple systems:
  - Non-parallel arrangement (see figure)
  - Lateral clearance =  $2 \times m$  (see section "5.5 Clearance from reflective Surfaces" on page 29)
  - Screening (e.g. by means of partitions)



## 5.7 Deflection Mirror



The range of possible applications can be significantly expanded through the use of a Deflection Mirror. Deflection Mirrors are available in two different variants:

- Z2UGxxx without housing
- SZ000EUxxxNN01 with Protection Column

A danger zone can be secured at several sides using only one Safety Light Curtain with the help of wenglor Deflection Mirrors. Range is reduced by approximately 10 % per mirror.

Further system components can be found in [section 3.5 on page 16](#) and in [section "5.1 System Overview" on page 20](#).

## 5.8 Electrical Connection

- Both safety outputs, OSSD1 and OSSD2, must be incorporated into the machine's power circuit.
- Functional earth can be optionally connected.

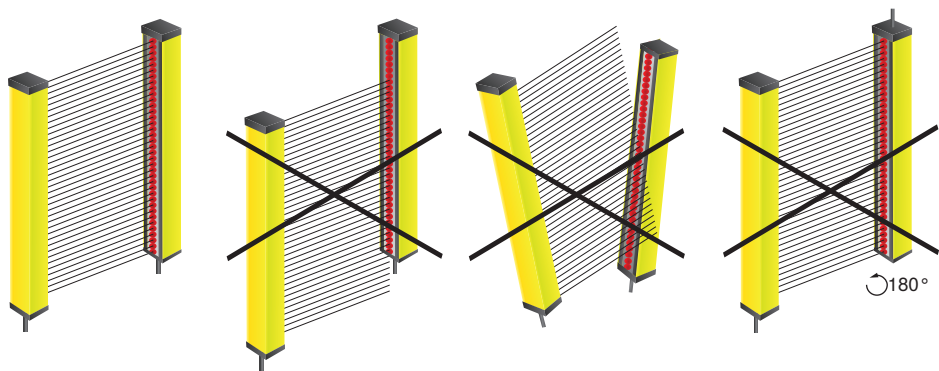


### NOTE!

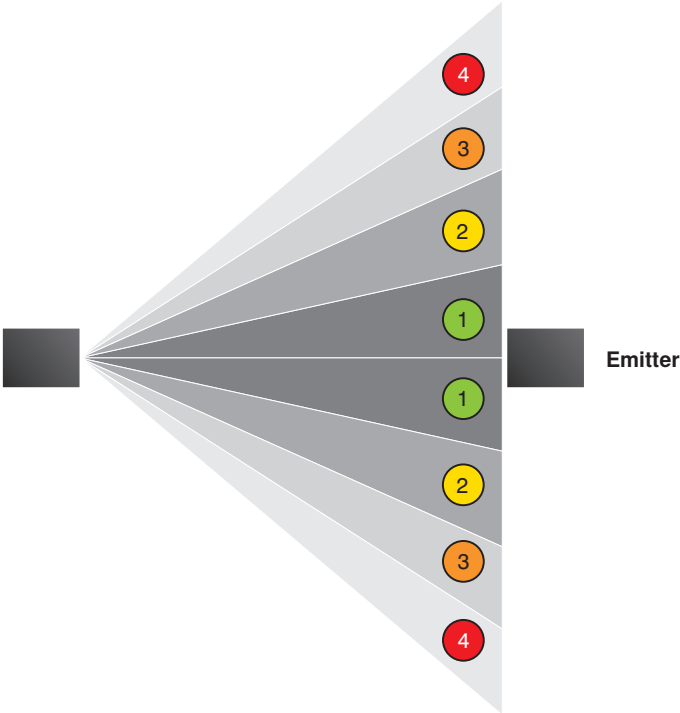
Selectable functions are chosen by means of corresponding wiring ([section "7.1 Initial Start-Up" on page 37](#) and [section "7.2 Overview of All Functions" on page 43](#)).

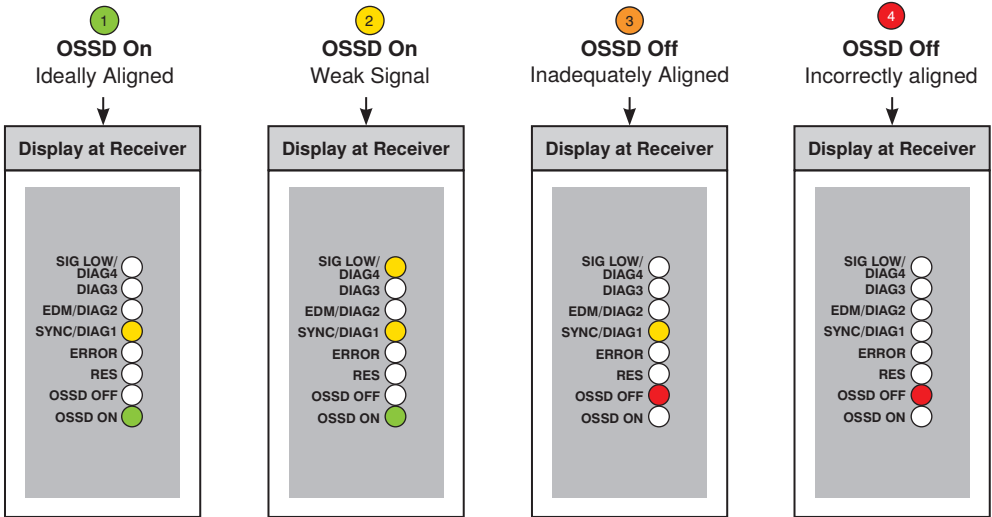
# 5.9 Optical Alignment

Prealignment:



View from Above





## 5.10 Diagnostics

### Conduct in case of fault:



#### NOTE!

- Shut down the machine.
- Analyze and eliminate the cause of error on the basis of the diagnostics information (see section 12.4 on page 64).
- If the error cannot be eliminated, please contact wenglor's support department.

#### Receiver



#### DANGER!

##### Risk of personal injury or property damage in case of non-compliance!

The system's safety function is disabled. Personal injury and damage to equipment.

- Do not operate in case of indeterminate malfunctioning.
- The machine must be shut down if the error cannot be unequivocally clarified or reliably eliminated.
- Conduct in case of fault as specified

- Displays which appear during normal operation are included in the appendix (see section "12.3 Display during Normal Operation" on page 63).
- Displays which appear in the event of an error are included in the appendix (see section "12.4 Display in Case of Error" on page 66).

# 6. Functions

## 6.1 Default Settings

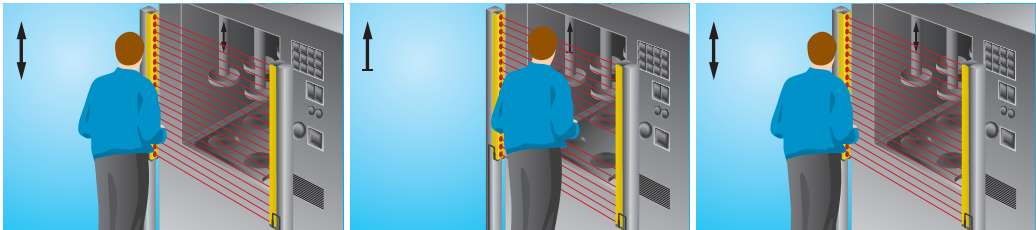
Device	Function	Default Setting
Receiver	Safety mode	Active (in the case of appropriate wiring)
	Start-up and restart inhibit	Inactive, is activated automatically by means of appropriate wiring
	Contactor monitoring	Inactive, is activated automatically by means of appropriate wiring
Emitter	Test function	Inactive, is activated when triggered during operation
	Range	High range (in the case of appropriate wiring)

## 6.2 Function definition

### Safety Mode (automatic operation)

[abc]

- In this operating mode, the switching outputs are disabled when the safety field is interrupted. The switching outputs are automatically enabled after interrupted of the safety field is ended.



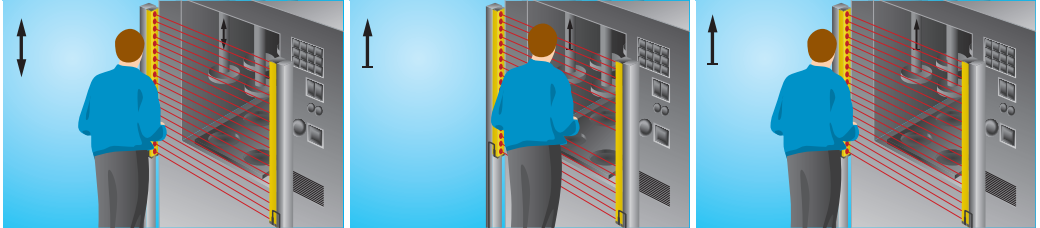
**NOTE!**

- Determine whether or not safety mode operation is permissible for the respective application.

## Start-Up and Restart Inhibit

### [abc]

- Start-up inhibit is activated along with the → restart inhibit function. When supply power is switched on (e.g. after a power failure), the safety outputs (OSSD) remain in the off state. Acknowledgement is accomplished by activating an acknowledgment key.
- Restart inhibit prevents a machine from starting back up automatically after the safety field has been interrupted. The machine can only be re-enabled by activating an acknowledgment key.



#### NOTE!

- The acknowledgment key must be mounted outside of the danger zone.
- The user must be able to see into the danger zone in an unobstructed fashion when activating the acknowledgement key.

## Contactors Monitoring

### [abc]

- Contactor monitoring is a function for which switching performance of the contacts at an external relay is dynamically monitored. The contacts must close fully within a specified period of time.
- Switching devices equipped with positively-driven NC contacts are a prerequisite for this function.

## Signal Output

### [abc]

- The signal output is a semiconductor output for auxiliary functions without safety monitoring.
- Additional read-out function: acknowledgment prompt.

## Test Function

[abc]

- If the test input is connected to plus, the transmission function is deactivated. The sensor can thus be tested for correct functioning. If the input is open or connected to minus, the transmission function is activated.

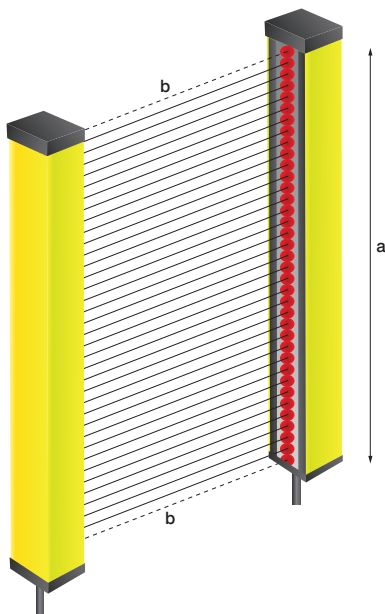
### NOTE!



- The ESPE is self-testing. No external test is required.
- Max. valid test duration: < 150 ms
- A test duration of  $\geq 150$  ms results in a warning (see section “12.3.2 Emitter” on page 65)
- A test duration of > 10 s results in an error (see section “12.4.2 Emitter” on page 68)

## Synchronization

- The emitter and the receiver are synchronized by means of optical synchronization beams. These are the upper and lowermost beams.



a = safety field height

b = synchronization beams



## 7. Settings

### 7.1 Initial Start-Up



**NOTE!**

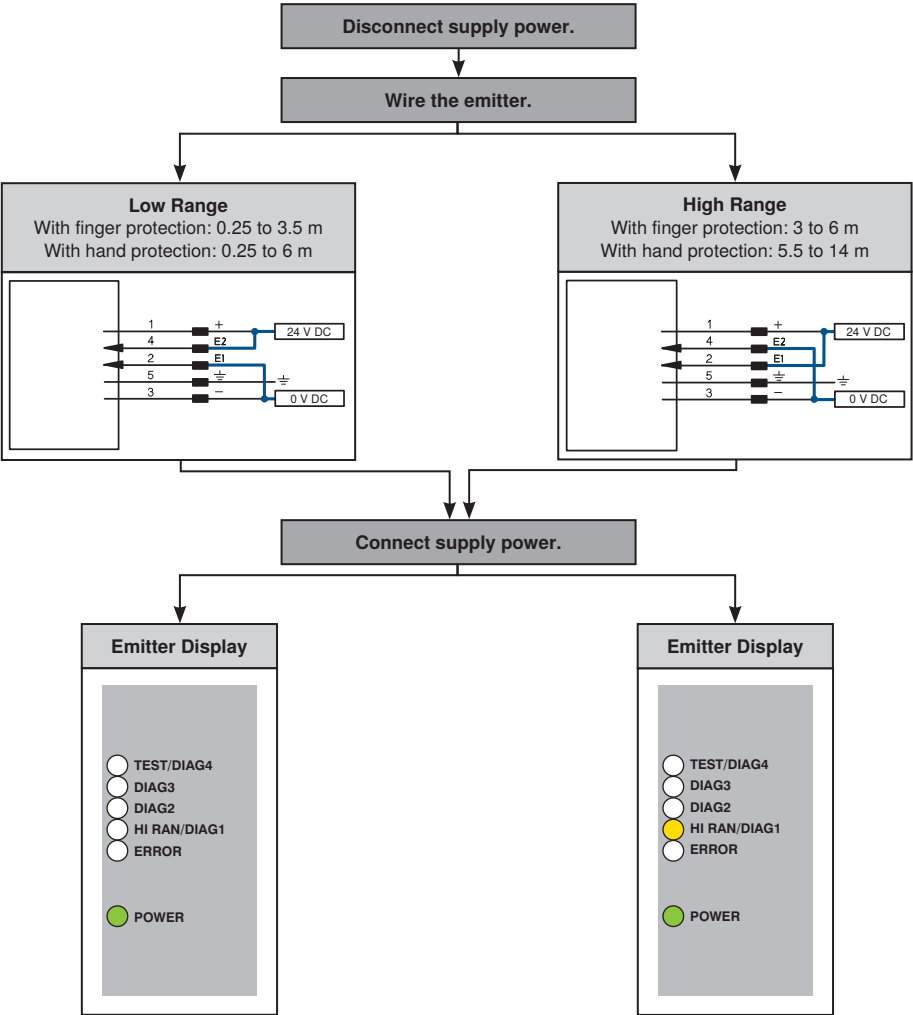
- For easy set-up and alignment, first select “safety mode without contactor monitoring”.
- Perform all adjustments without supply power.

**General procedure:**

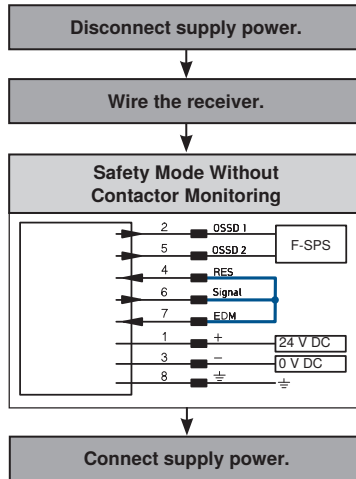
1. Adjust the emitter.
2. Adjust the receiver.
3. Align the sensor optically.
4. Adjust other functions as required.
5. Safety Light Curtain ready for operation

Initial Start-Up Procedure

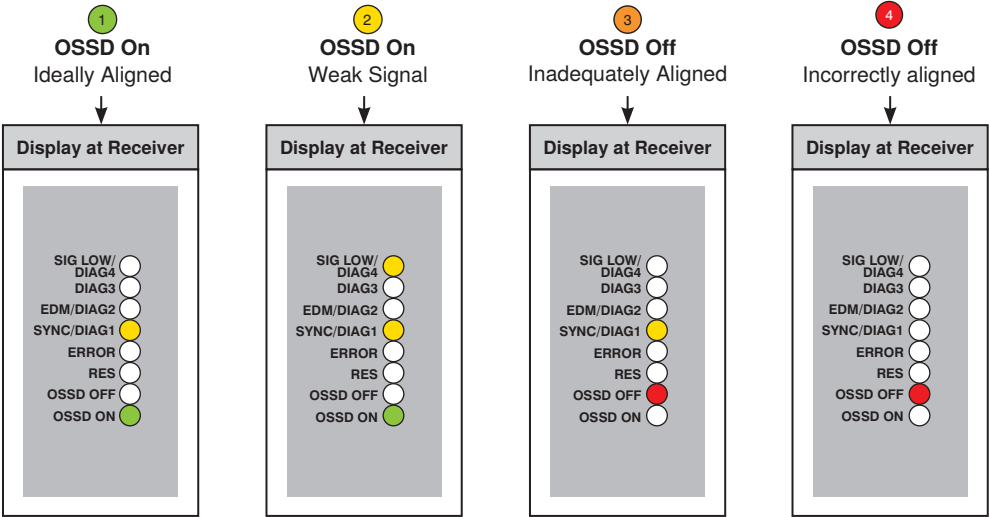
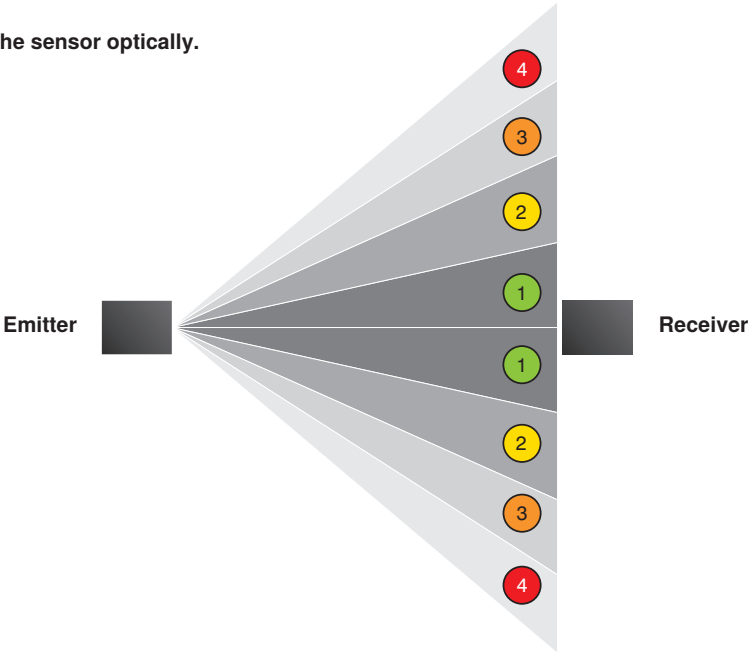
1. Adjust the emitter.



## 2. Adjust the receiver.



3. Align the sensor optically.

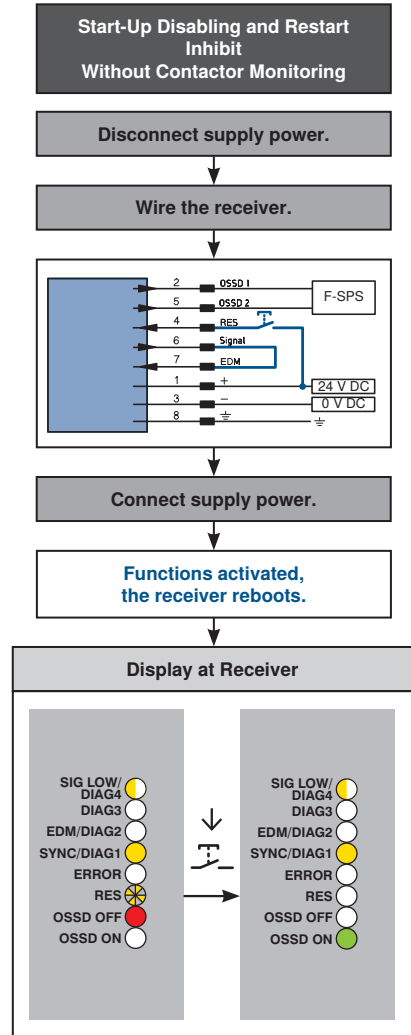
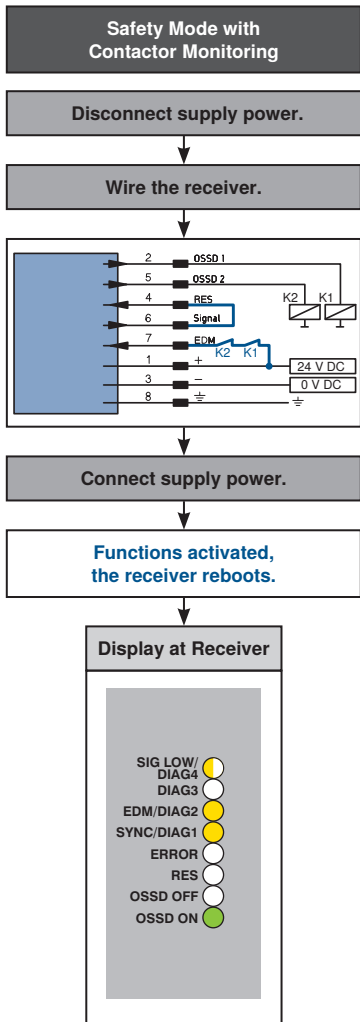


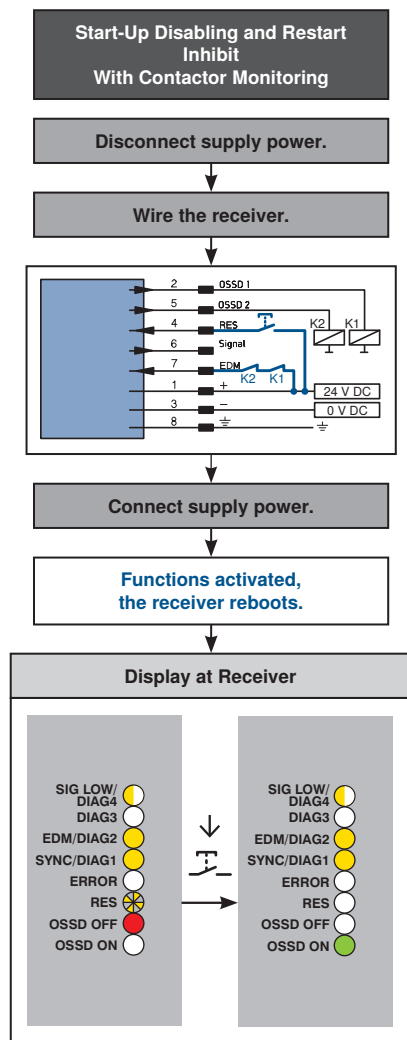
When the maximum range of the sensors is exploited, “SIG LOW/DIAG4” may appear at the display even if they are ideally aligned. The illustration applies to the safety mode without contactor monitoring.

#### 4. Adjust other functions as required.

Select from:

- Safety mode with contactor monitoring
- Start-up and restart inhibit without contactor monitoring
- Start-up and restart inhibit with contactor monitoring (see page 42)





## 5. Safety Light Curtain ready for operation

## 7.2 Overview of All Functions

Emitter Settings		Receiver Settings	
Range	<a href="#">section 7.3</a>	Safety mode without contactor monitoring	<a href="#">section 7.4</a>
Test function	<a href="#">section 7.9</a>	Safety mode with contactor monitoring	<a href="#">section 7.5</a>
		Start-up and restart inhibit without contactor monitoring	<a href="#">section 7.6</a>
		Start-up and restart inhibit with contactor monitoring	<a href="#">section 7.7</a>
		Signal output	<a href="#">section 7.8</a>

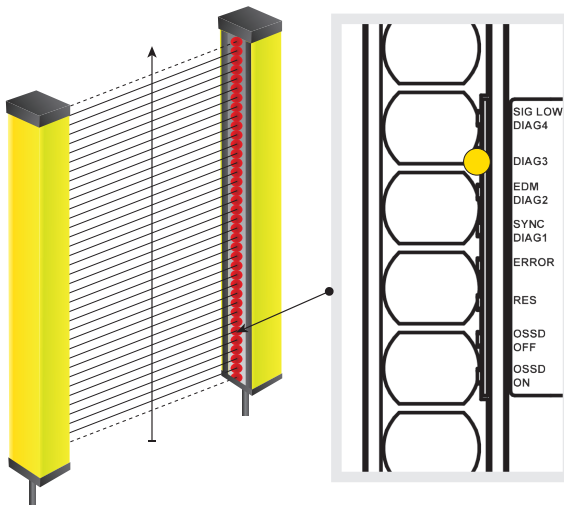


### NOTE!

In order to accept the modified configuration, a test object must be passed through the safety field (beginning at the sensor connection on the control panel side up to the other end) within 30 seconds after electrical connection and activation of supply voltage. Interruption is confirmed by LED DIAG3 at the receiver.

**This is always necessary when switching to a “less safe” operating mode:**

- From restart inhibit to safety mode
- From contactor monitoring to operation without contactor monitoring



An overview of parameters configuration for the receiver is included in the index (see [section “12.2 Overview of Receiver Parameters Configuration”](#) on page 63).

## 7.3 Adjusting Range



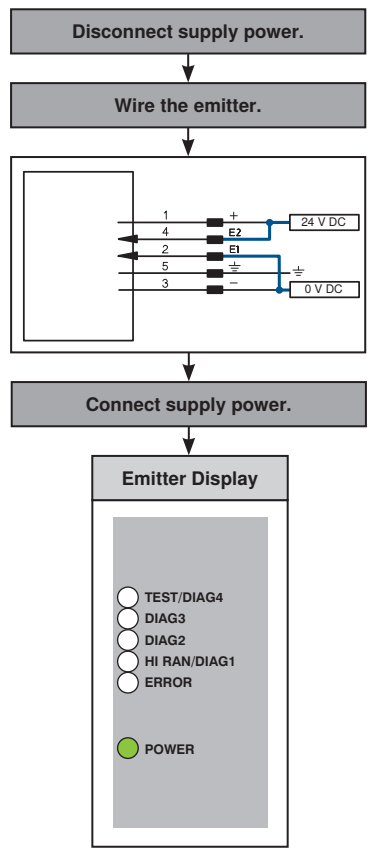
**DANGER!**  
**Risk of personal injury or property damage in case of incorrectly adjusted range!**  
The range setting is safety relevant. If it's set too high, **bleed-over reflection may occur.**

- Range must be suitably adjusted for each respective application.

### 7.3.1 Low Range

- Low range with 14 mm resolution: 0.25 to 3.5 m
- Low range with 30 mm resolution: 0.25 to 6 m

**Procedure:**

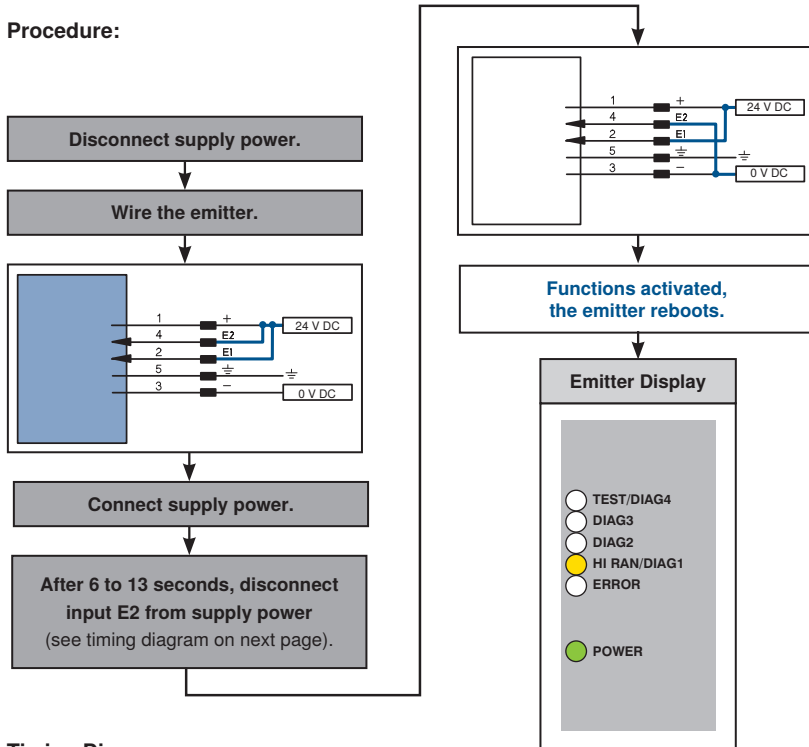




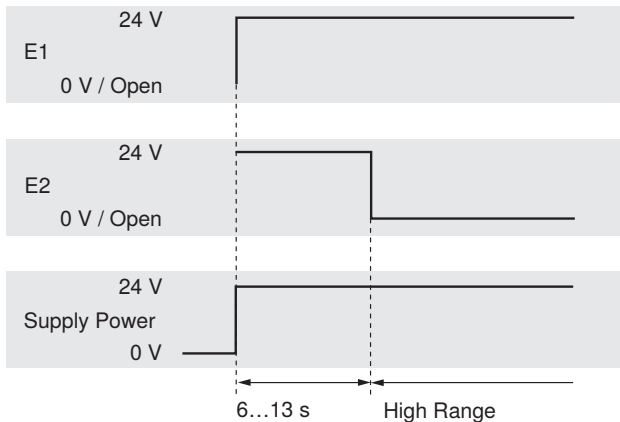
### 7.3.2 High Range

- High range with 14 mm resolution: 3 to 6 m
- High range with 30 mm resolution: 5.5 to 14 m

#### Procedure:

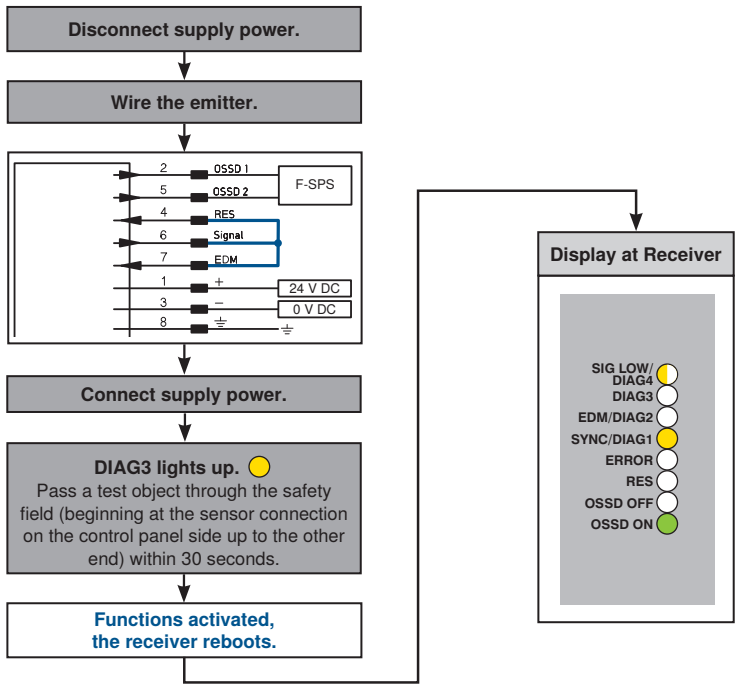


#### Timing Diagram

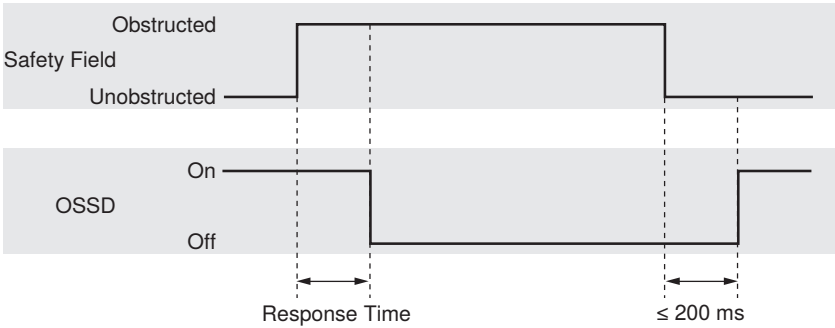


## 7.4 Safety Mode Without Contactor Monitoring

Procedure:



### Timing Diagram



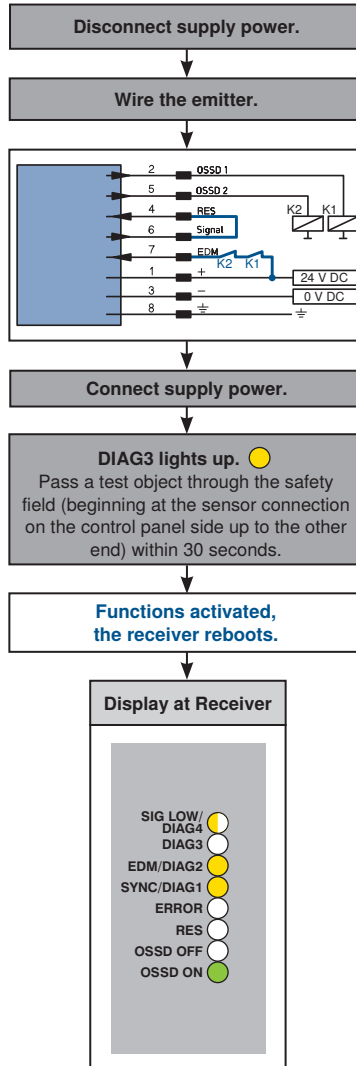
## 7.5 Safety Mode With Contactor Monitoring



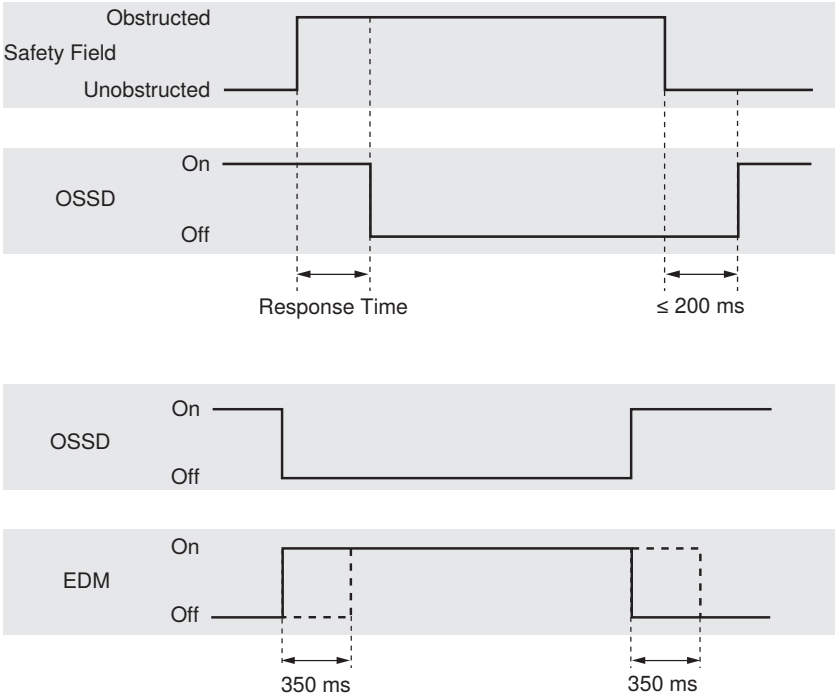
### NOTE!

Make sure that the ESPE is ideally aligned. This is easiest to see in the “safety mode without contactor monitoring” configuration (see section “7.1 Initial Start-Up” on page 37).

### Procedure:



Timing-Diagramme



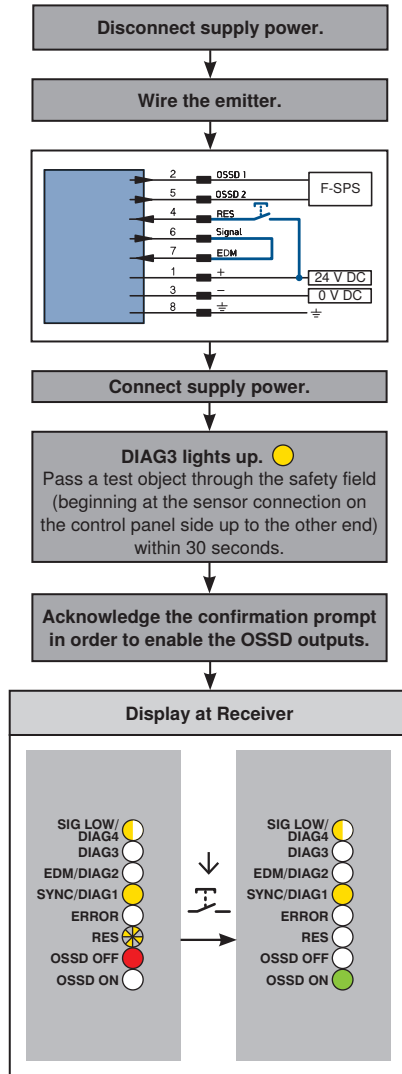
## 7.6 Start-Up and Restart Inhibit Without Contactor Monitoring



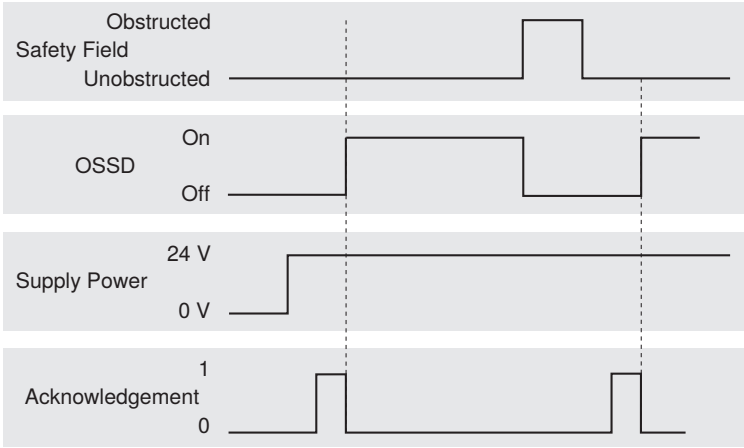
### NOTE!

Make sure that the ESPE is ideally aligned. This is easiest to see in the “safety mode without contactor monitoring” configuration (see section “7.1 Initial Start-Up” on page 37).

### Procedure:



Timing-Diagramm



Acknowledgement duration: 0.1 to 4 seconds (see technical data)



- NOTE!**
- DIAG3 only lights up if restart inhibit with contactor monitoring has been previously selected.
  - If the Light Curtain was previously configured for “safety mode with contactor monitoring” or “safety mode without contactor monitoring”, the LED does not light up.

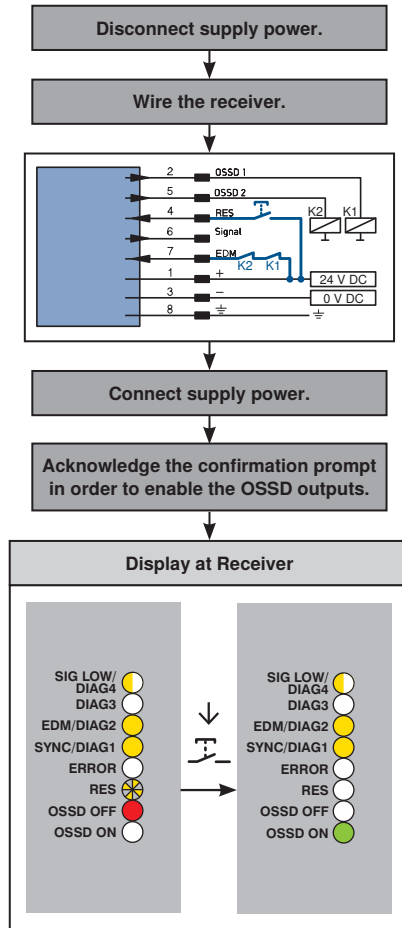
## 7.7 Start-Up and Restart Inhibit With Contactor Monitoring



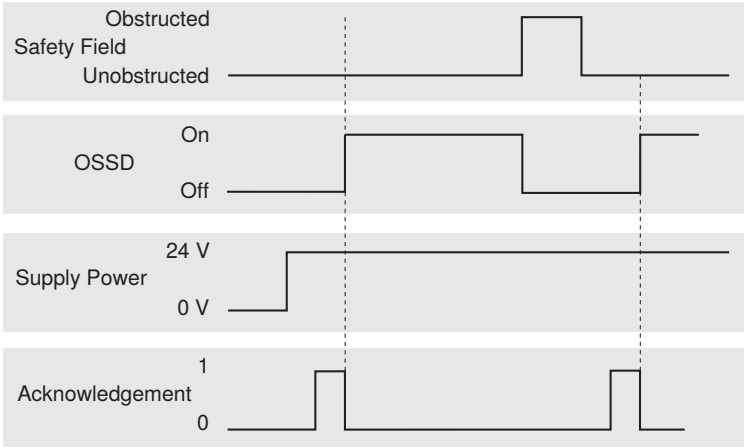
### NOTE!

- Make sure that the ESPE is ideally aligned. This is easiest to see in the “safety mode without contactor monitoring” configuration ([see section “7.1 Initial Start-Up” on page 37](#)).

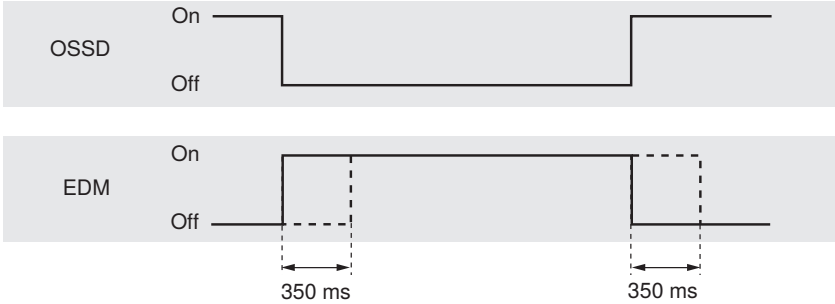
### Procedure:



Timing Diagrams



Acknowledgement duration: 0.1 to 4 seconds (see technical data)





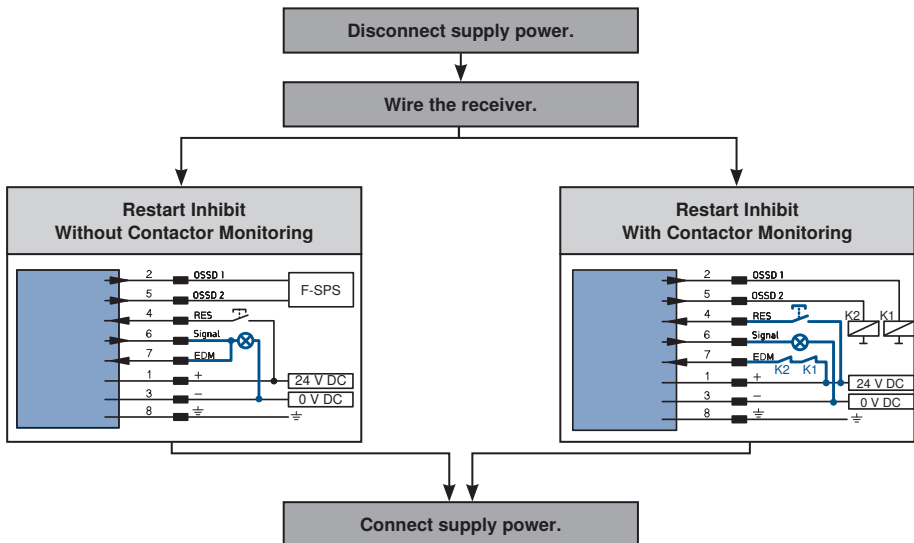
## 7.8 Signal output



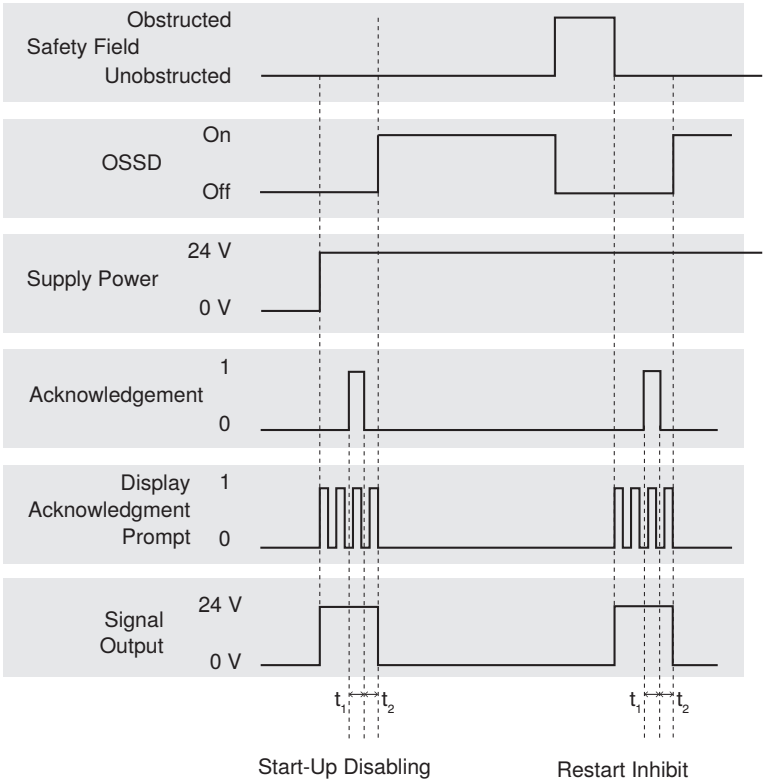
### NOTE!

The signal output provides information indicating whether or not an acknowledgement request is pending (with active start-up or restart inhibit).

### Procedure:



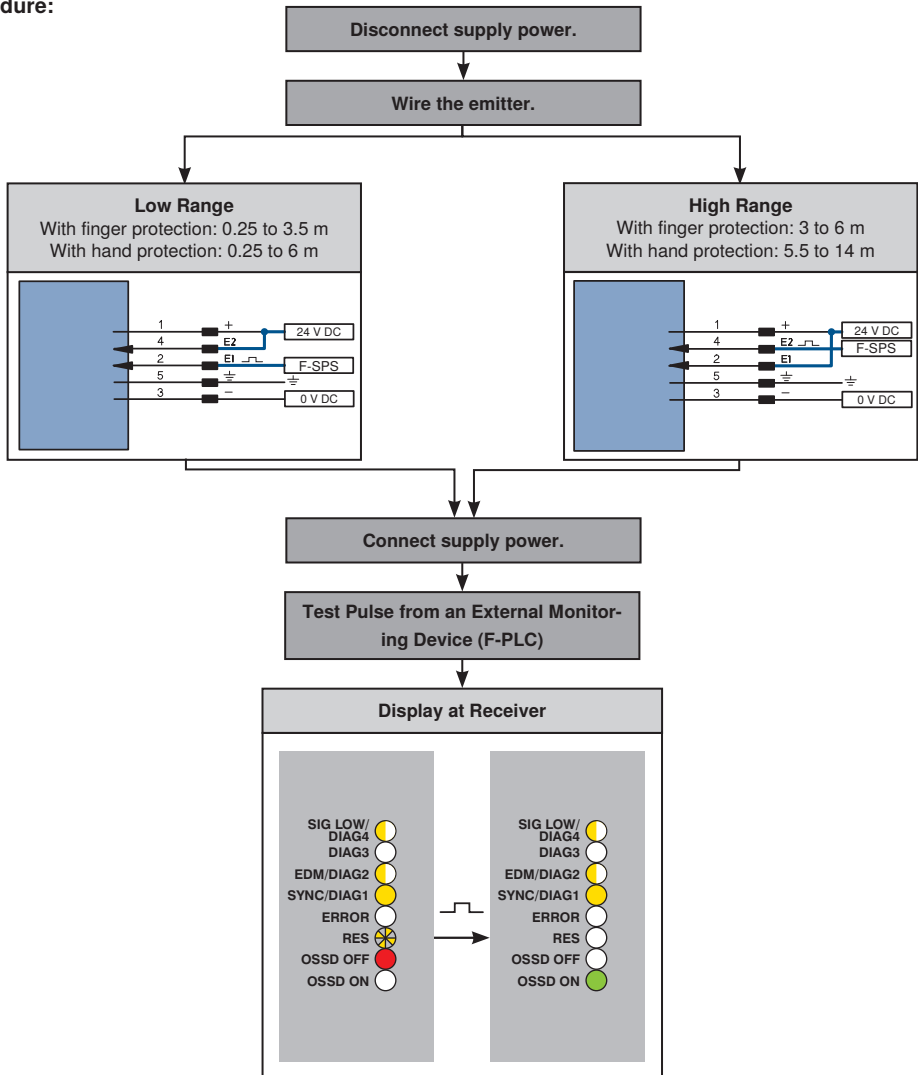
Timing-Diagramm



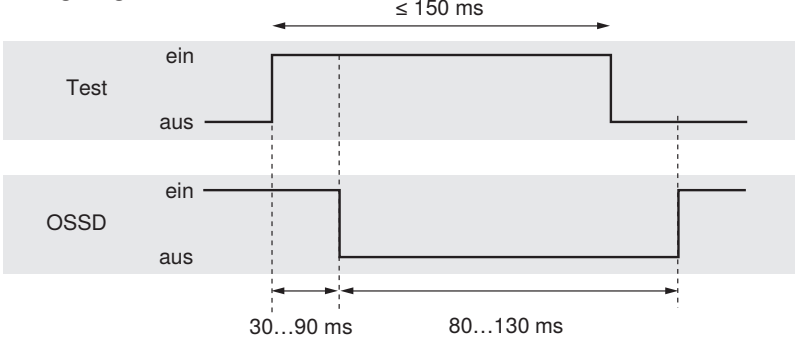
$t_1$  - Acknowledgement duration: 0.1 to 4 s     $t_2$  - On-time: 30 to 120 ms

## 7.9 Test Function

Procedure:



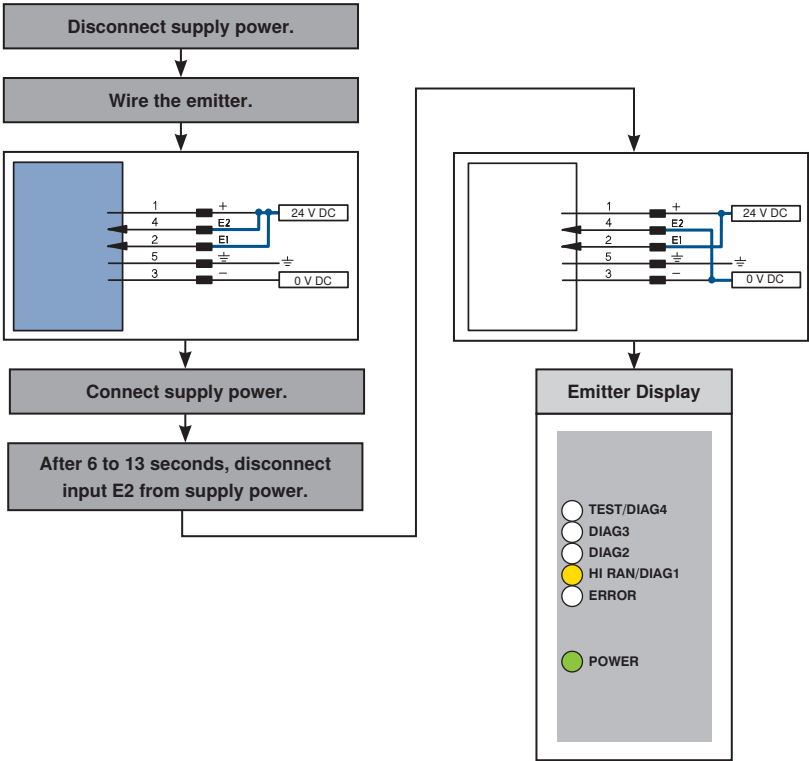
Timing-Diagramm



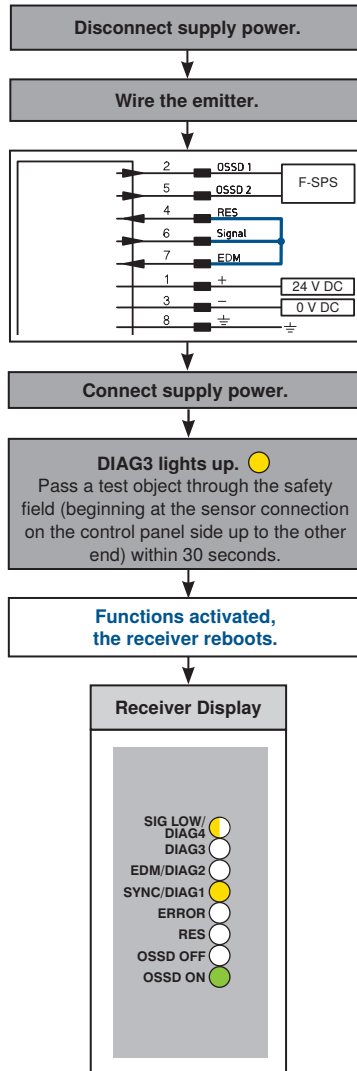
7.10 Restoring Default Settings

If the desired configuration has been interrupted (error, timeout etc.), the sensor can be returned to its default settings with the help of the following procedure.

Emitter



## Receiver



## 8. Testing

### 8.1 Testing Prior to Initial Start-Up

Inspection to assure that the ESPE has been correctly selected in accordance with local ordinances, and testing to assure that they provide the required protection when used for their intended purpose.

**Execute testing:**

- Prior to initial start-up
- After making changes to the machine
- After the machine has been shut down for a lengthy period of time
- After modifying or repairing the machine



**NOTE!**

- Observe regulations regarding the training of operating personnel by experts before they begin work.
- The company which operates the machine is responsible for training.

**Testing**

	Effectiveness of the ESPE must be assured in all operating modes which can be selected at the machine. <ul style="list-style-type: none"><li>• Testing according to checklist (<a href="#">see section “12.5 Initial Start-Up Checklist” on page 69</a>).</li></ul>
--	---



**NOTE!**

- Work at the machine must be immediately stopped if any impairment of the safety function is detected.
- If the safety function is impaired, test the effectiveness of the ESPE at the machine once again in accordance with the checklist ([see section “12.5 Initial Start-Up Checklist” on page 69](#)).

## 8.2 Annual Inspection

Inspection once a year or before expiration of deadlines specified by applicable national regulations.

### Inspection

	The machine has not undergone any changes or manipulations which might affect the safety system.
	The ESPE has not undergone any changes or manipulations which might affect the safety system.
	The ESPE is correctly connected to the machine.
	The machine's response time (including ESPE) has not increased in comparison with response time during initial start-up.
	Cables, plugs and mounting components must be in flawless condition.

#### NOTE!



- Work at the machine must be immediately stopped if any impairment of the safety function is detected.
- If the safety function is impaired, test the effectiveness of the ESPE at the machine once again in accordance with the checklist ([see section "12.5 Initial Start-Up Checklist" on page 69](#)).

### 8.3 Regular Inspection

The described checks are intended to confirm compliance with national / international safety regulations.



**NOTE!**

- Regulations governing operator induction by specialist personnel must be observed before work is commenced.
- The company which operates the machine is responsible for training.

Regular inspections must be conducted by a person who has been authorized and engaged to do so by the company which operates the machine. The frequency (e.g. daily, at shift changes, etc.) must be determined based on the risk assessment for the application.



**DANGER!**

- Work on the machine must be immediately stopped if any impairment of the safety function is detected.
- Once the situation has been resolved, the effectiveness of the ESPE must be checked again according to the checklist for initial start-up (see section “12.5 Initial Start-Up Checklist” on page 69).



**NOTE!**

- The supplied sticker “Instructions for regular inspection” must be mounted in a clearly visible location close to the relevant ESPE.
- Do not clean the ESPE with solvents or cleaning agents which could damage the device (aggressive, abrasive, scratching).

**Inspection**

	The ESPE may not demonstrate any visible damage.
	The lens cover may not be scratched or contaminated.
	It must be impossible to approach the danger zone without passing through the safety field of the ESPE.
	Cables, plugs and mounting components must be in flawless condition.



### Testing the effectiveness of the ESPE:

- Testing may only be conducted when hazardous motion has been switched off.
- Testing must be conducted with a test rod, and not by reaching in with the hand.
- Test rod diameter: in accordance with ESPE resolution



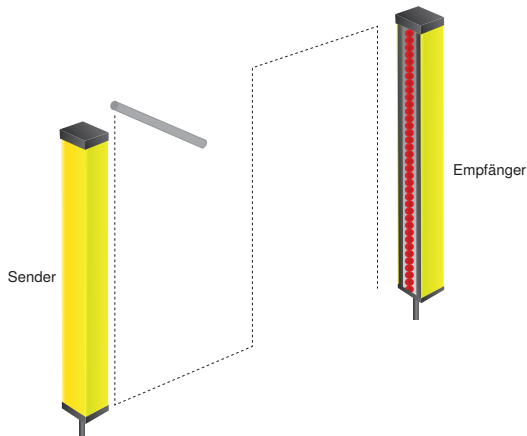
### Testing the “automatic start-up function” (safety mode):

- The OSSD ON display must light up before testing is started.
- Pass the test rod through the entire safety field as shown in the figure.
- The OSSD OFF display must be lit up as long as the test rod is in the safety field.



### Testing the “restart inhibit” function:

- The RES display must blink before testing is started.
- Pass the test rod through the safety field as shown in the figure.
- The OSSD OFF display must remain lit up as long as the test rod is in the safety field.
- The RES display may not light up as long as the test rod is in the safety field.



# 9. Maintenance



**NOTE!**

- This wenglor sensor is maintenance-free.
- Instructions regarding annual (see section “8.2 Annual Inspection” on page 59) and regular inspection section 8.3 on page 60 must be adhered to.

# 10. Shutdown

The sensor must be disconnected from supply power for shutdown. The sensor neither contains nor gives off any environmentally harmful substances. It consumes only a minimum of energy and resources.

# 11. Proper Disposal

wenglor sensoric GmbH does not accept the return of unusable or irreparable products. Respectively valid national waste disposal regulations apply to product disposal.

# 12. Appendix

## 12.1 Change Index, Operating Instructions

Version	Date	Description/Change
01	23.11.2015	Initial version of the operating instructions
02	21.04.2016	Adjust display of housing dimensions (see section 3.2 )
03	04.05.2016	Adjust EU declaration of conformity (see section 12.8 )
04	11.07.2019	Adjust EU declaration of conformity (see section 12.8 )
05	06.10.2021	Adjust (see section 8.3 )
06	20.04.2022	Adjust section 7.3, section 7.8 , section 7.10
07	11.07.2022	Adjust (see section 3.2 )
08	08.02.2023	New section 12.7

## 12.2 Overview of Receiver Parameters Configuration

The receiver's parameters are configured by means of corresponding wiring of pins 4, 6 and 7.

	Safety Mode Without EDM	Safety Mode With EDM	RES Without EDM	RES With EDM
	<a href="#">section 7.4</a>	<a href="#">section 7.5</a>	<a href="#">section 7.6</a>	<a href="#">section 7.1</a>
Pin 4 (RES)	Jumper to pin 6	Jumper to pin 6	24 V via pushbutton	24 V via pushbutton
Pin 6 (signal output)	–	–	Optionally to PLC or signaling module	Optionally to PLC or signaling module
Pin 7 (EDM)	Jumper to pin 6	24 V via closed feedback loop	Jumper to pin 6	24 V via closed feedback loop

## 12.3 Display during Normal Operation

### 12.3.1 Receiver

Display	Description
<div><div>SIG LOW/DIAG4</div><div>DIAG3</div><div>EDM/DIAG2</div><div>SYNC/DIAG1</div><div>ERROR</div><div>RES</div><div>OSSD OFF</div><div>OSSD ON</div></div>	<ul style="list-style-type: none"><li>Receiver and emitter are not synchronized.</li></ul>
<div><div>SIG LOW/DIAG4</div><div>DIAG3</div><div>EDM/DIAG2</div><div>SYNC/DIAG1</div><div>ERROR</div><div>RES</div><div>OSSD OFF</div><div>OSSD ON</div></div>	<ul style="list-style-type: none"><li>OSSD is activated.</li><li>Receiver and emitter are synchronized.</li><li>Safety mode or start-up and restart inhibit is active.</li><li>Contactor monitoring is active. EDM/DIAG2</li><li>Contactor monitoring is inactive. EDM/DIAG2</li><li>Ideally aligned SIG LOW/DIAG4</li><li>Weak signal SIG LOW/DIAG4</li></ul>

<div> <div>SIG LOW/DIAG4</div> <div>DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div> </div>	<ul style="list-style-type: none"> <li>• OSSD is off</li> <li>• Receiver and emitter are synchronized.</li> <li>• Start-up and restart inhibit is active.</li> <li>• Acknowledgment prompt</li> <li>• Contactor monitoring is active EDM/DIAG2 ●</li> <li>• Contactor monitoring is inactive EDM/DIAG2 ○</li> <li>• Ideally aligned SIG LOW/DIAG4 ○</li> <li>• Weak signal SIG LOW/DIAG4 ●</li> </ul>
<div> <div>SIG LOW/DIAG4</div> <div>DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div> </div>	<ul style="list-style-type: none"> <li>• OSSD is off</li> <li>• Beam interruption through the entire safety field is required from the cable connection to other end.</li> <li>• Contactor monitoring is active EDM/DIAG2 ●</li> <li>• Contactor monitoring is inactive EDM/DIAG2 ○</li> <li>• Ideally aligned SIG LOW/DIAG4 ○</li> <li>• Weak signal SIG LOW/DIAG4 ●</li> <li>• Receiver and emitter are synchronized. SIG LOW/DIAG1 ●</li> <li>• Receiver and emitter are not synchronized. SIG LOW/DIAG1 ○</li> </ul>







When the maximum range of the sensors is exploited, “SIG LOW/DIAG4” may appear at the display even if they are ideally aligned.







12.3.2 Emitter

Display	Description	Display	Description
<div><div>○ TEST/DIAG4</div><div>○ DIAG3</div><div>○ DIAG2</div><div>○ HI RAN/DIAG1</div><div>○ ERROR</div><div><div>● POWER</div></div></div>	<ul style="list-style-type: none"><li>• Supply power on</li><li>• Low range</li></ul>	<div><div>● TEST/DIAG4</div><div>○ DIAG3</div><div>○ DIAG2</div><div>○ HI RAN/DIAG1</div><div>○ ERROR</div><div><div>● POWER</div></div></div>	<ul style="list-style-type: none"><li>• Supply power on</li><li>• Low range</li><li>• Test duration of 150 ms exceeded</li></ul>
<div><div>○ TEST/DIAG4</div><div>○ DIAG3</div><div>○ DIAG2</div><div>● HI RAN/DIAG1</div><div>○ ERROR</div><div><div>● POWER</div></div></div>	<ul style="list-style-type: none"><li>• Supply power on</li><li>• High range</li></ul>	<div><div>● TEST/DIAG4</div><div>○ DIAG3</div><div>○ DIAG2</div><div>● HI RAN/DIAG1</div><div>○ ERROR</div><div><div>● POWER</div></div></div>	<ul style="list-style-type: none"><li>• Supply power on</li><li>• High range</li><li>• Test duration of 150 ms exceeded</li></ul>





# 12.4 Display in Case of Error

## 12.4.1 Receiver

Display	Description	Display	Description
<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>OSSD 2 short circuit to plus</li></ul>  <ul style="list-style-type: none"><li>Eliminate short circuit to plus.</li></ul>	<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>Contactor is not released.</li><li>Contacts are fused together.</li></ul>  <ul style="list-style-type: none"><li>Inspect the contactor (connection and function).</li></ul>
<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>OSSD 2 short circuit to ground</li></ul>  <ul style="list-style-type: none"><li>Eliminate short circuit to ground.</li></ul>	<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>Invalid configuration Restart inhibit detected</li></ul>  <ul style="list-style-type: none"><li>For safety mode operation, remove reset button and activate in accordance with <a href="#">section 7.4 on page 46</a>.</li><li>For start-up and restart inhibit, connect reset button correctly and activate in accordance with <a href="#">section 7.6 on page 49</a>.</li></ul>
<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>Contactor does not pick up.</li></ul>  <ul style="list-style-type: none"><li>Inspect the contactor (connection and function).</li></ul>	<div>SIG LOW/DIAG4 DIAG3</div> <div>EDM/DIAG2</div> <div>SYNC/DIAG1</div> <div>ERROR</div> <div>RES</div> <div>OSSD OFF</div> <div>OSSD ON</div>	<ul style="list-style-type: none"><li>Invalid configuration, contactor monitoring detected</li></ul>  <ul style="list-style-type: none"><li>For contactor monitoring, connect contactor correctly and activate in accordance with <a href="#">section 7.5 on page 47</a> or <a href="#">section 7.7 on page 51</a>.</li><li>Without contactor monitoring: remove contactor and deactivate in accordance with <a href="#">section 7.4 on page 46</a> or <a href="#">section 7.6 on page 49</a>.</li></ul>

<p>SIG LOW/DIAG4 DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• OSSD 1 short circuit to plus</li> </ul>  <ul style="list-style-type: none"> <li>• Eliminate short circuit to plus.</li> </ul>	<p>SIG LOW/DIAG4</p> <p>DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• Supply power overvoltage/undervoltage</li> </ul>  <ul style="list-style-type: none"> <li>• Provide for supply power within the specified limits.</li> </ul>
<p>SIG LOW/DIAG4</p> <p>DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• OSSD 1 short circuit to ground</li> </ul>  <ul style="list-style-type: none"> <li>• Eliminate short circuit to ground.</li> </ul>	<p>SIG LOW/DIAG4</p> <p>DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• Internal error</li> </ul>  <ul style="list-style-type: none"> <li>• Restart the system.</li> <li>• If restart is not successful, contact wenglor's support department.</li> </ul>
<p>SIG LOW/DIAG4</p> <p>DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• Extraneous light/emitter</li> </ul>  <ul style="list-style-type: none"> <li>• Remove the interfering emitter.</li> </ul>	<p>SIG LOW/DIAG4</p> <p>DIAG3</p> <p>EDM/DIAG2</p> <p>SYNC/DIAG1</p> <p>ERROR</p> <p>RES</p> <p>OSSD OFF</p> <p>OSSD ON</p>	<ul style="list-style-type: none"> <li>• Configuration change not completed</li> </ul>  <ul style="list-style-type: none"> <li>• Repeat configuration</li> </ul>

12.4.2 Emitter

Display	Description	Display	Description
<div><div>TEST/DIAG4</div><div>DIAG3</div><div>DIAG2</div><div>HI RAN/DIAG1</div><div>ERROR</div></div> <div>POWER</div>	<div><div>Invalid range setting</div><div></div><div>Set range to high or low.</div></div>	<div><div>TEST/DIAG4</div><div>DIAG3</div><div>DIAG2</div><div>HI RAN/DIAG1</div><div>ERROR</div></div> <div>POWER</div>	<div><div>Invalid range setting</div><div>Test duration exceeded</div><div></div><div>Set range to high or low.</div></div>
<div><div>TEST/DIAG4</div><div>DIAG3</div><div>DIAG2</div><div>HI RAN/DIAG1</div><div>ERROR</div></div> <div>POWER</div>	<div><div>Supply power overvoltage/undervoltage</div><div></div><div>Provide for supply power within the specified limits.</div></div>	<div><div>TEST/DIAG4</div><div>DIAG3</div><div>DIAG2</div><div>HI RAN/DIAG1</div><div>ERROR</div></div> <div>POWER</div>	<div><div>Parameters configuration for large range without executing the procedure in accordance with 7.3.2</div><div></div><div>Restart the system.</div><div>If restart is not successful, contact wenglor's support department.</div><div>Execute procedure in accordance with 7.3.2.</div></div>



## 12.5 Initial Start-Up Checklist

This checklist is intended to provide assistance during initial start-up.



### NOTE!

The checklist does not eliminate the need for testing before initial start-up or periodic tests conducted by appropriately trained personnel.

1 Standards and Directives, ESPE Selection		
Are the safety precautions based on the directives/standards which are applicable for the machine?	Yes	No
Are the utilized directives and standards listed in the declaration of conformity?	Yes	No
Is the safety device in compliance with the required PL (EN ISO 13849-1)/SILcl (EN 62061) from the risk assessment?	Yes	No
2 Safety Clearance		
Has safety clearance been calculated in accordance with the applicable standards?	Yes	No
Have the response time of the ESPE, the response time of any included safety evaluation unit, and machine over-travel time been taken into account in the calculation?	Yes	No
Has machine over-travel time been measured, specified, documented (at the machine and/or in the machine's documentation) and adapted to the ESPE installation setup?	Yes	No
Is required safety clearance between the point of danger and the safety field adhered to?	Yes	No
3 Access to the Point of Danger		
Is it only possible to access the point of danger via the ESPE's safety field?	Yes	No
Is it assured that persons are unable to remain within the danger zone unprotected (e.g. by means of mechanical protection against side-stepping), and are the implemented measures protected against manipulation?	Yes	No
Have additional mechanical protective measures been installed which prevent reaching under, over or around the safety field, and are they protected against manipulation?	Yes	No
4 Installation		
Have the components of the ESPE been correctly attached and secured against loosening, shifting and rotation after alignment?	Yes	No
Is the external condition of the ESPE and all associated system components flawless?	Yes	No
Has the acknowledgement key for resetting the ESPE been correctly installed outside of the danger zone, and is it functional?	Yes	No
5 Incorporation into the Machine		
Have both OSSDs been incorporated into the downstream machine controls?	Yes	No
Have they been connected in accordance with the wiring diagrams?	Yes	No
Are the switching elements which are controlled by the ESPE (e.g. contactors, valves) monitored by EDM?	Yes	No
Have required protective measures against electric shock been effectively implemented?	Yes	No

## 6 Functionality

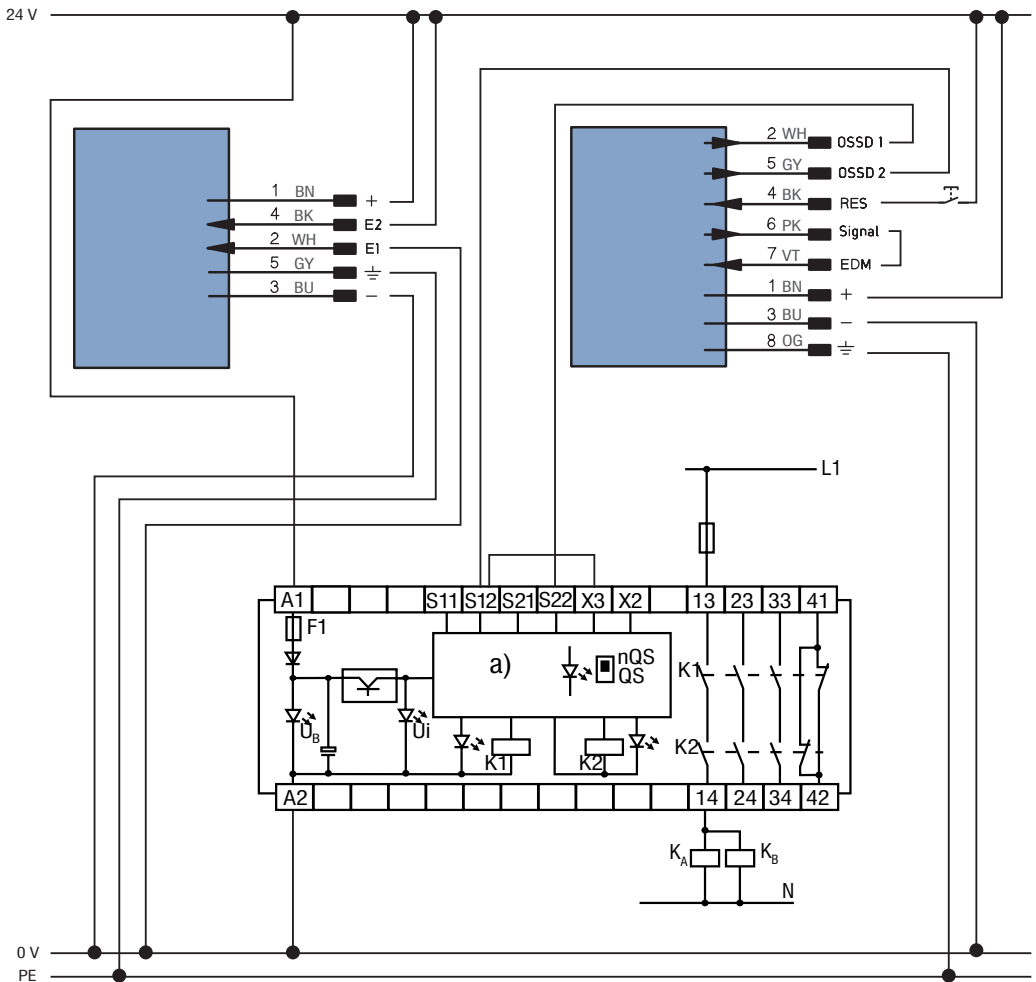
Is the ESPE effective during the entire duration of the machine's hazardous motion?.	Yes	No
Is hazardous motion stopped when the ESPE is disconnected from supply power, and does the acknowledgment key have to be activated in order to reset the machine after supply power has been restored?	Yes	No
If a hazardous state has been initialized, is it stopped when the ESPE is switched off, if the operating mode or any of the function types are changed, or if switching to another safety device occurs?	Yes	No
Are the specified safety functions effective in all of the machine's operating modes?	Yes	No
Has the safety function been tested in accordance with the inspection instructions in the operating instructions?	Yes	No
Have the instructions for regular inspection of the ESPE been attached such that they are plainly visible and legible for operating personnel.	Yes	No

## 12.6 Connection Examples

Note: Functional earth can be optionally connected.

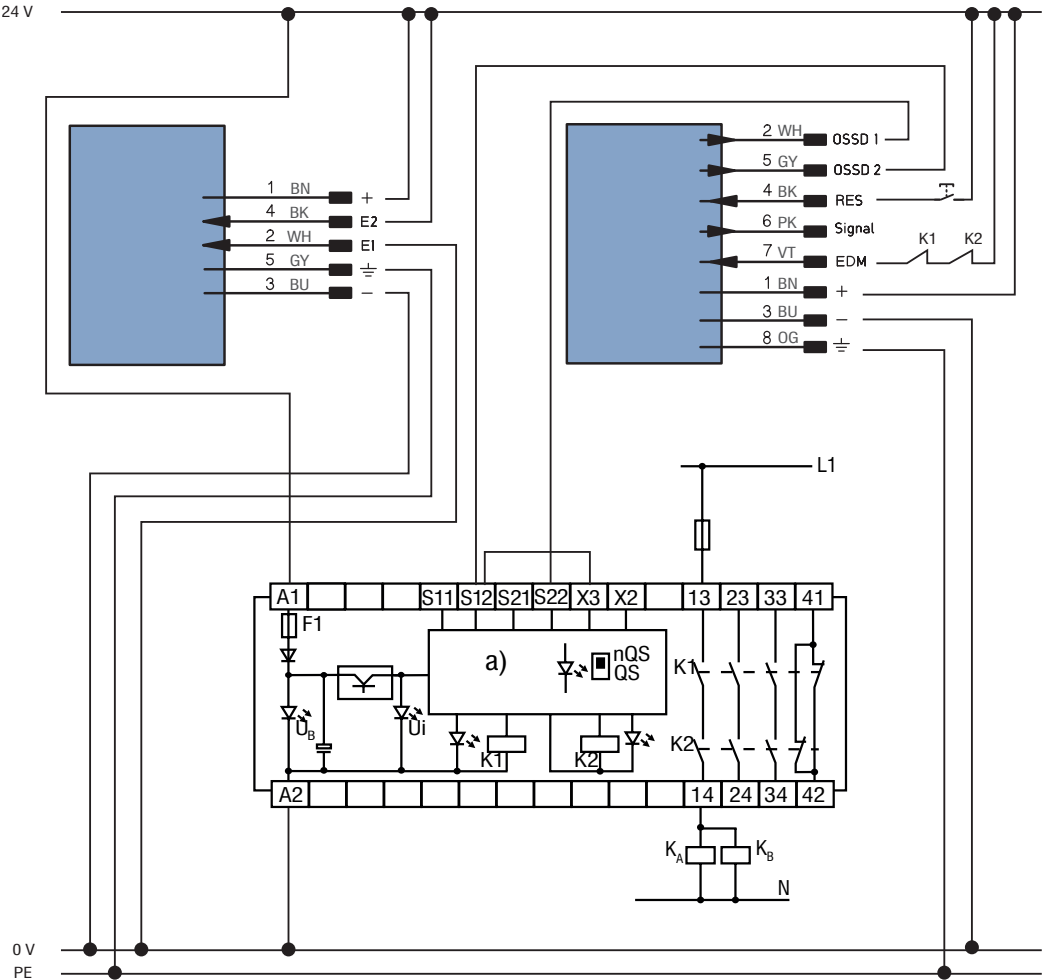
### 12.6.1 Restart Inhibit Without Contactor Monitoring at SEMG4xxx

- RES via SEMG
- No EDM
- Low range
- SR4B3B01S



12.6.2 Restart Inhibit and Contactor Monitoring at SEMG4xxx

- RES via SEMG
- EDM via SEMG
- Low range
- SR4B3B01S





- No RES
- No EDM
- Low range



## 12.7 Additions for applications down to temperature range –30 °C

Devices from the SEMG range can be used under the following conditions at temperatures down to –30 °C.



### CAUTION!

The electrical connections may only be subjected to low mechanical loads at temperatures below –25 °C.

Replacement for technical data, [section 3, page 9](#):

Temperature range	–30...55 °C
Storage temperature	–30...60 °C
Mission time TM (EN ISO 13849-1)	15 a

Replacement for housing dimensions, tables in [section 3.2, page 12](#):

### Resolution: 14 mm

Order Number	SFH (mm)	L (mm)	L1	A (mm)	B (mm)	Max. weight per sensor (kg)
SEMGx71	250	250	269	0	0	0,38
SEMGx72	310	310	330	0	0	0,53
SEMGx73	460	460	480	0	0	0,69
SEMGx74	610	610	630	0	0	0,84
SEMGx75	761	761	780	0	0	0,99
SEMGx76	911	911	930	0	0	1,15
SEMGx77	1058	1061	1080	0	–3*	1,30
SEMGx78	1208	1211	1230	0	–3*	1,45
SEMGx79	1358	1361	1380	0	–3*	1,61
SEMGx80	1508	1511	1531	0	–3*	1,76
SEMGx81	1658	1661	1681	0	–3*	1,91
SEMGx82	1808	1811	1831	0	–3*	2,07

\* –3 means: The housing protrudes over the safety field by 3 mm.

**Resolution: 30 mm**

Order Number	SFH (mm)	L (mm)	L1	A (mm)	B (mm)	Max. weight per sensor (kg)
SEMGx52	326	312	332	14	0	0,53
SEMGx53	486	462	482	14	10	0,69
SEMGx54	626	612	632	14	0	0,84
SEMGx55	787	763	782	14	10	0,99
SEMGx56	927	913	932	14	0	1,15
SEMGx57	1087	1063	1082	14	10	1,30
SEMGx58	1227	1213	1232	14	0	1,45
SEMGx59	1387	1363	1382	14	10	1,61
SEMGx60	1527	1513	1533	14	0	1,76
SEMGx61	1687	1663	1683	14	10	1,91
SEMGx62	1827	1813	1833	14	0	2,07



## 12.8 EU Declaration of Conformity

The EU declaration of conformity can be found on our website at [www.wenglor.com](http://www.wenglor.com) in the product's separate download area.

### EU Konformitätserklärung EU Declaration of Conformity (DoC)



Name und Anschrift des Herstellers / Name and address of manufacturer:

wenglor sensoric GmbH  
wenglor Straße 3  
88069 Tett nang / GERMANY

Diese Erklärung gilt für die folgenden Produkte: This declaration applies to the following products:

**SEMG4...**  
**SEMG5...**  
**SEMG6...**

Wir bestätigen die Übereinstimmung mit den  
grundlegenden Anforderungen der Europäischen  
Richtlinien

We confirm compliance with the essential  
requirements of the European Directives

Richtlinie / Directive

Fundstelle / Reference

EMV / EMC

2014/30/EU

Amtsblatt / Official Journal

L 96 29.03.2014

Maschinen / MD

2006/42/EG

Amtsblatt / Official Journal

L 157 9.06.2006

Folgende harmonisierte Normen wurden  
angewandt:

The following harmonized standards have been  
used:

EN 61496-1:2013 (Type 4)  
IEC 61496-2:2013 (Type 4)  
EN 62061:2005 + Cor.:2010 + A1:2013 + A2:2015  
(SIL CL 3)

EN ISO 13849-1:2015 (Cat. 4, PL e)  
EN 50178:1997  
EN 61000-6-4:2007+A1:2011  
EN 61508:2010 (parts 1-3, SIL 3)

Produkt-Beschreibung

Product description

Sicherheits-Lichtvorhang  
Berührungslos wirkende Schutz Einrichtung  
Sicherheits-Bauteil nach 2006/42/EG Anhang IV  
Seriennummer: LL Typenschild

Safety Light Curtain  
Electro-Sensitive Protective Equipment  
Safety component per 2006/42/EC annex IV  
Serial Number: See rating plate

Benannte Stelle / Zertifikat Nr.

TÜV SÜD Product Service GmbH  
Ridlerstraße 65  
D-80339 München

Notified Body / Certificate Nr.

NB Nr. 0123  
Z10 040594 036 Rev. 00

Dr. Alexander Ohl ist bevollmächtigt, die techni-  
schen Unterlagen zusammenzustellen.

Dr. Alexander Ohl is authorized to compile the  
technical documentation.

Diese Erklärung stellvertretend für den Hersteller  
wird abgegeben durch:

On account of the manufacturer, this declaration  
is given by:

Dr. Alexander Ohl

Leiter Forschung & Entwicklung / Head of Research & Development

Tett nang, 01.07.2019

Ort / Place Datum / Date

Unterschrift / Signature